



FACULTY OF PHYSICS
AND APPLIED COMPUTER SCIENCE



Machine learning pipeline for $B_{(s,d)}^0 \rightarrow D_{(s)}^{\pm(*)} K^{\pm(*)}$ decay

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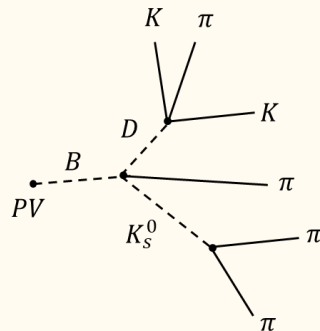
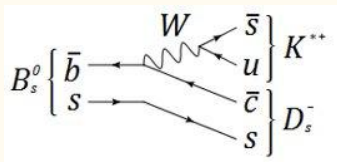
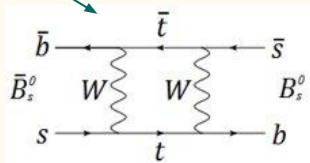
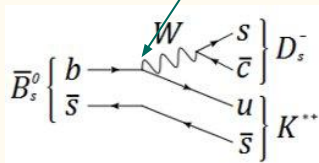
Outline

- Motivation
- Tools
- Signal and background proxy
- Training variables
- Classifier response and metrics
- Plots for reference channel
- Summary

Motivation

Measurement of γ angle of CKM matrix

$$\begin{pmatrix} d' \\ s' \\ b' \end{pmatrix} = \begin{pmatrix} V_{ud} & V_{us} & V_{ub} \\ V_{cd} & V_{cs} & V_{cb} \\ V_{td} & V_{ts} & V_{tb} \end{pmatrix} \begin{pmatrix} d \\ s \\ b \end{pmatrix} = \begin{pmatrix} |V_{ud}| & |V_{us}| & |V_{ub}|e^{-i\gamma} \\ -|V_{cd}| & |V_{cs}| & |V_{cb}| \\ |V_{td}|e^{i\beta} & -|V_{ts}|e^{i\beta_s} & |V_{tb}| \end{pmatrix} \begin{pmatrix} d \\ s \\ b \end{pmatrix}$$



Goal: Create ML pipeline

Tools

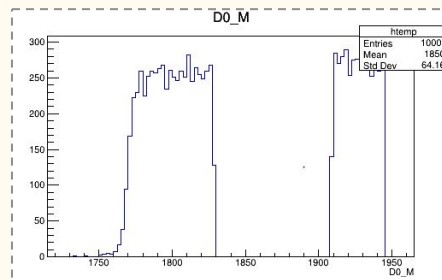
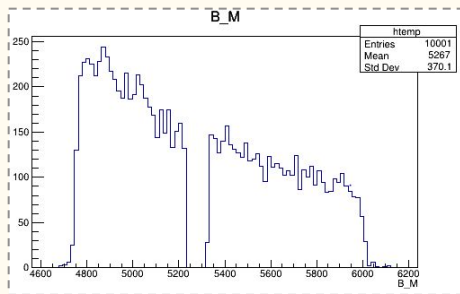


NumPy

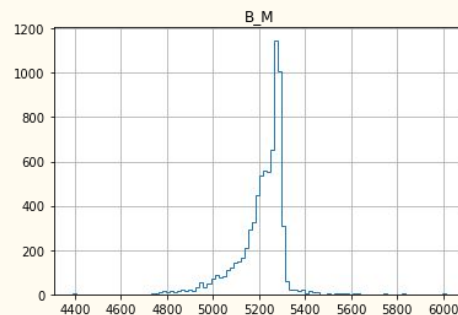


Signal and background proxy

Background proxy - sidebands from data

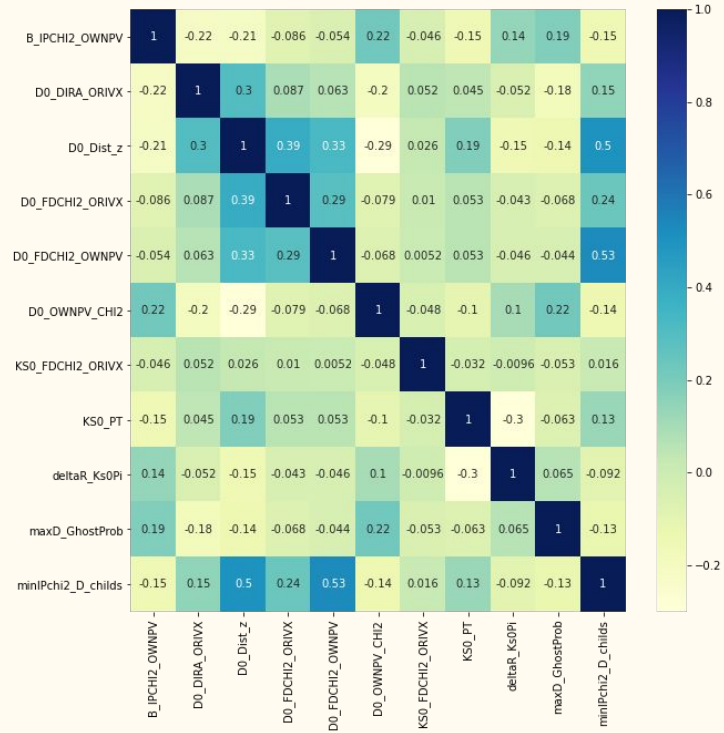
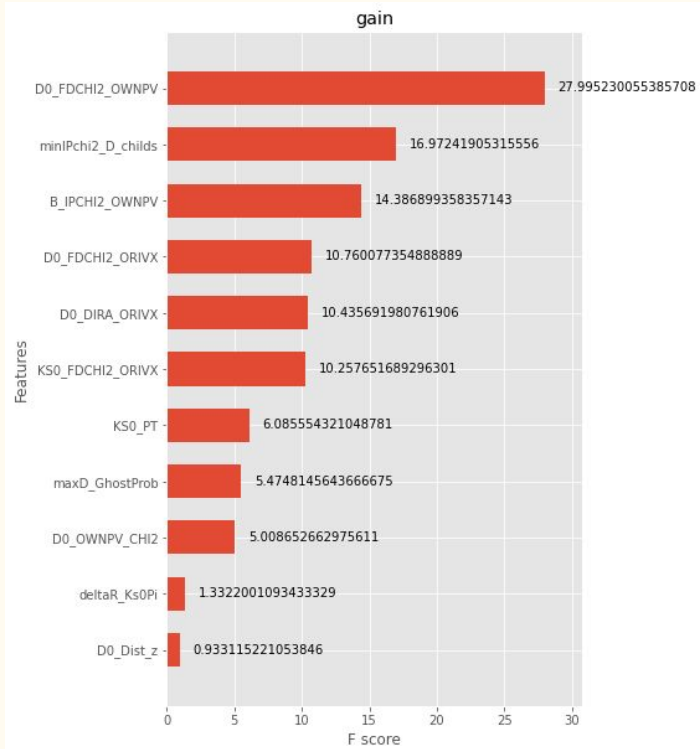


Signal proxy - Monte Carlo sample

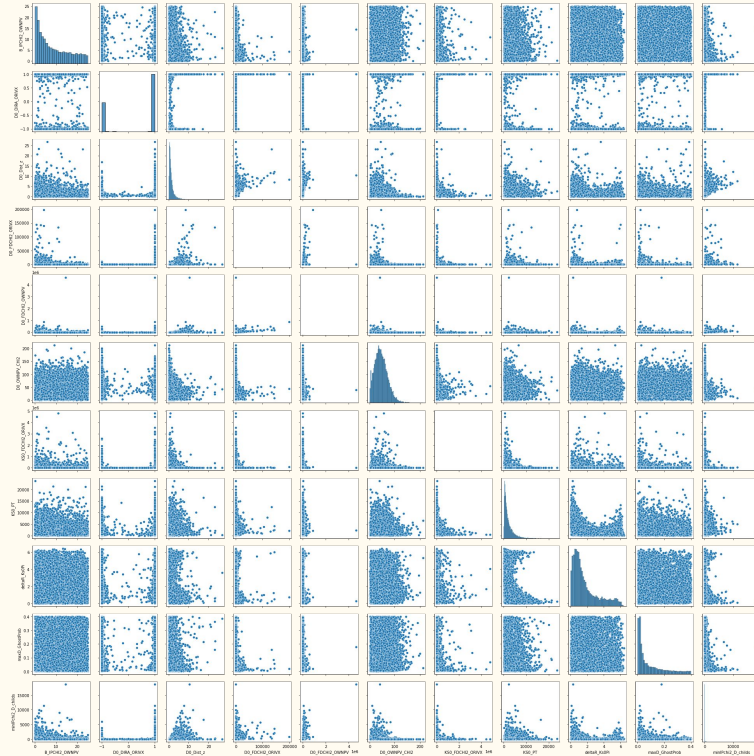


Train/test split - 50/50

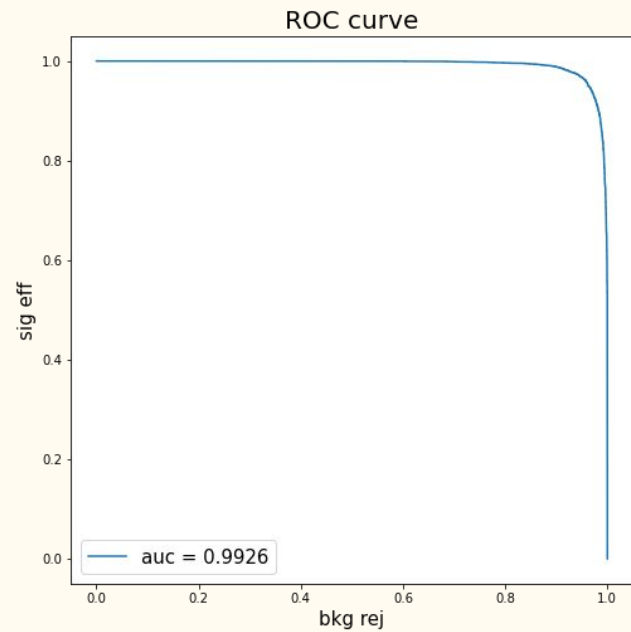
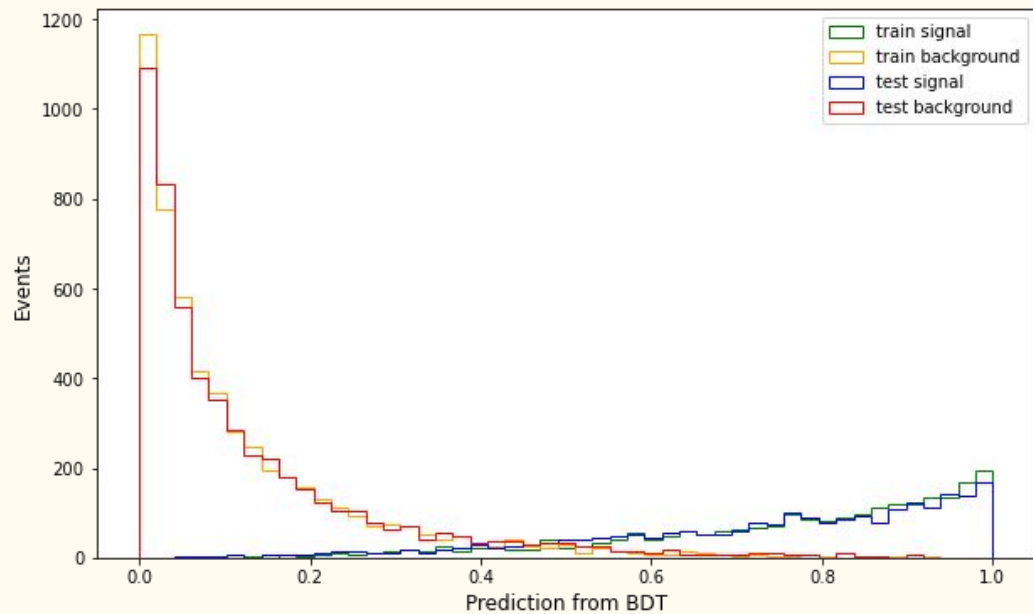
Training variables



Training variables



Classifier response and metrics



Classifier response and metrics

Accuracy = 0.9612

$$ACC = \frac{TP + TN}{P + N} = \frac{TP + TN}{TP + TN + FP + FN}$$

Precision = 0.9423

$$PPV = \frac{TP}{TP + FP} = 1 - FDR$$

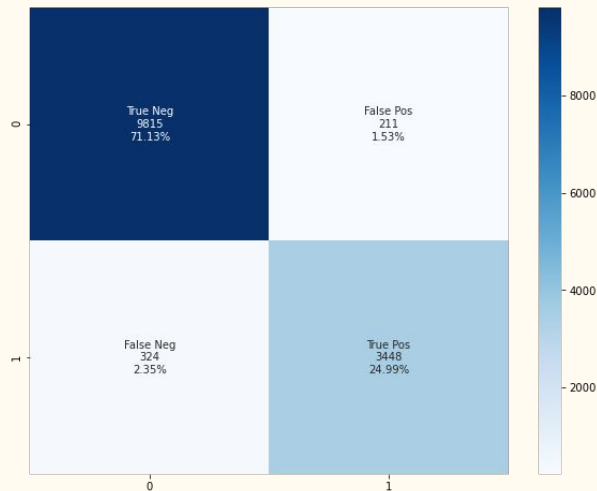
Recall = 0.9141

$$TPR = \frac{TP}{P} = \frac{TP}{TP + FN} = 1 - FNR$$

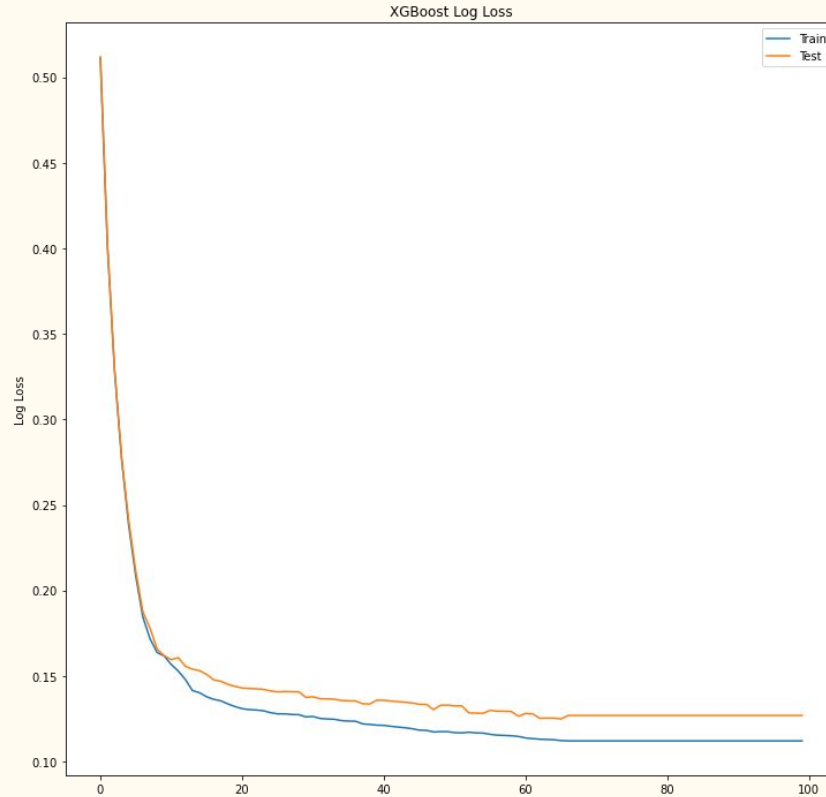
F1 = 0.9280

$$F_1 = 2 \times \frac{PPV \times TPR}{PPV + TPR} = \frac{2TP}{2TP + FP + FN}$$

confusion matrix

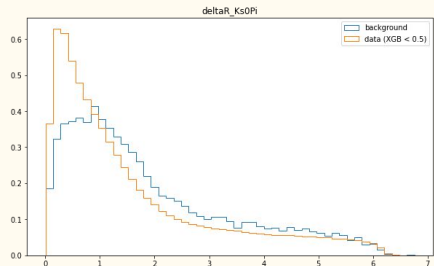
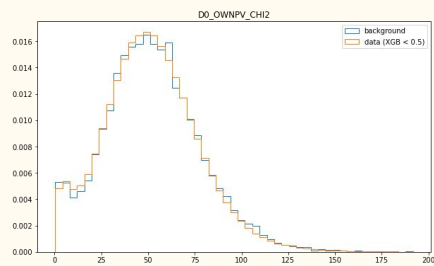
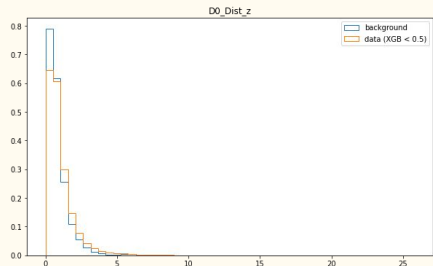
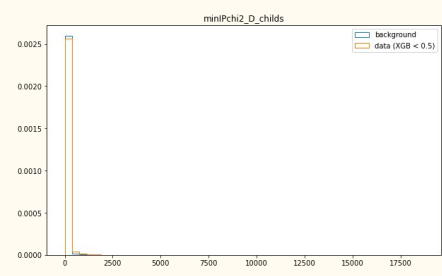
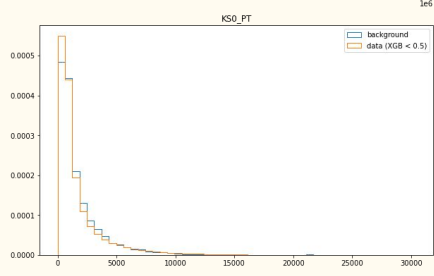
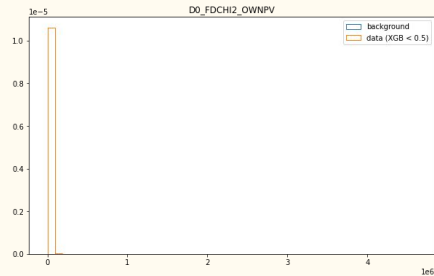
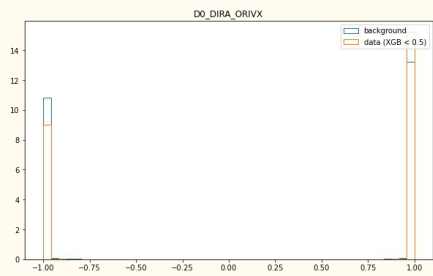
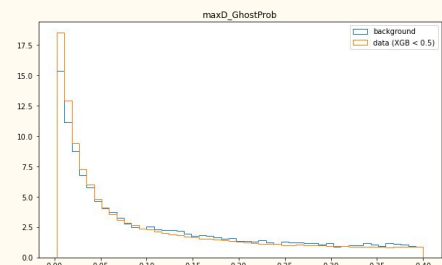
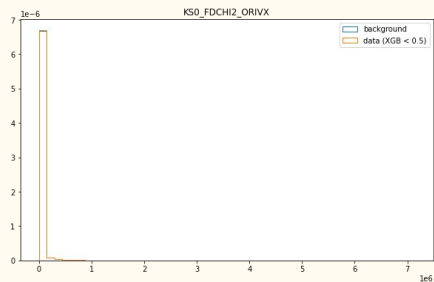
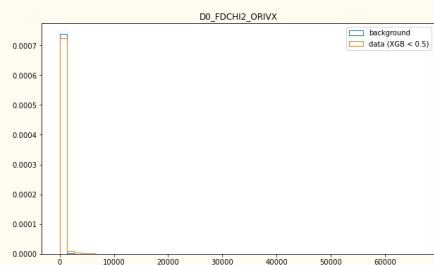
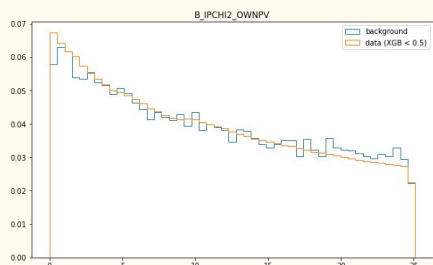


Classifier response and metrics

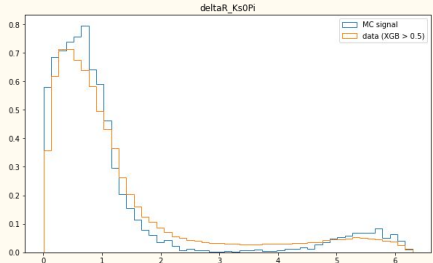
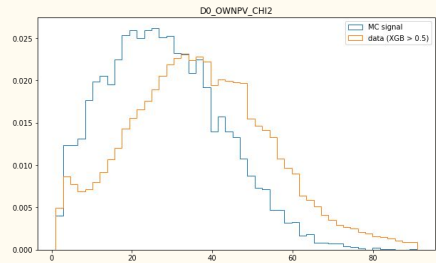
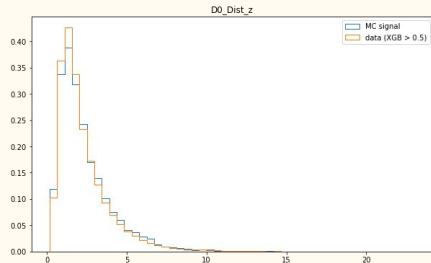
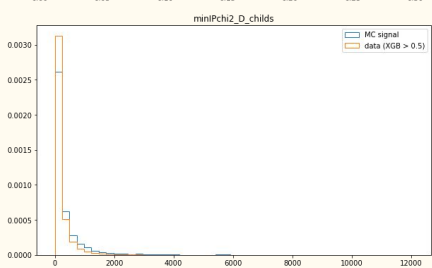
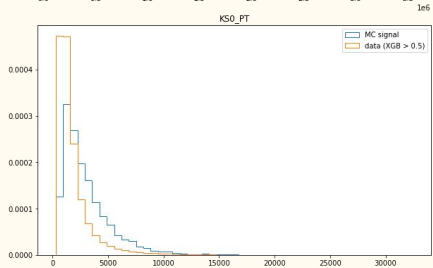
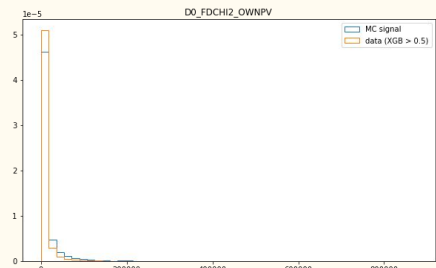
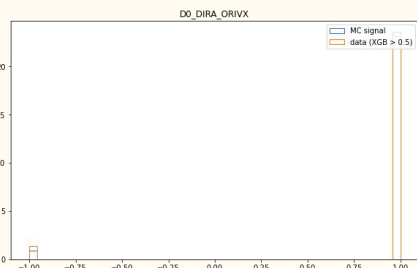
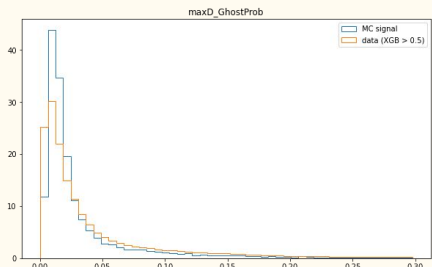
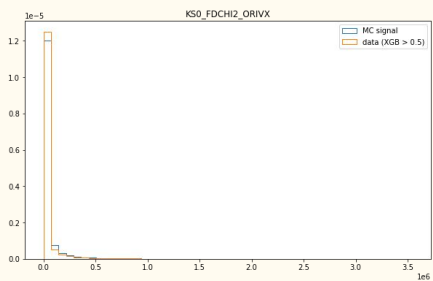
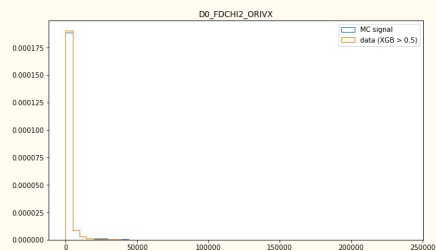
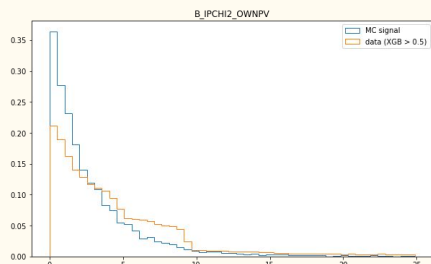


Training and testing curves are very close to each other. Model is not overtrained.

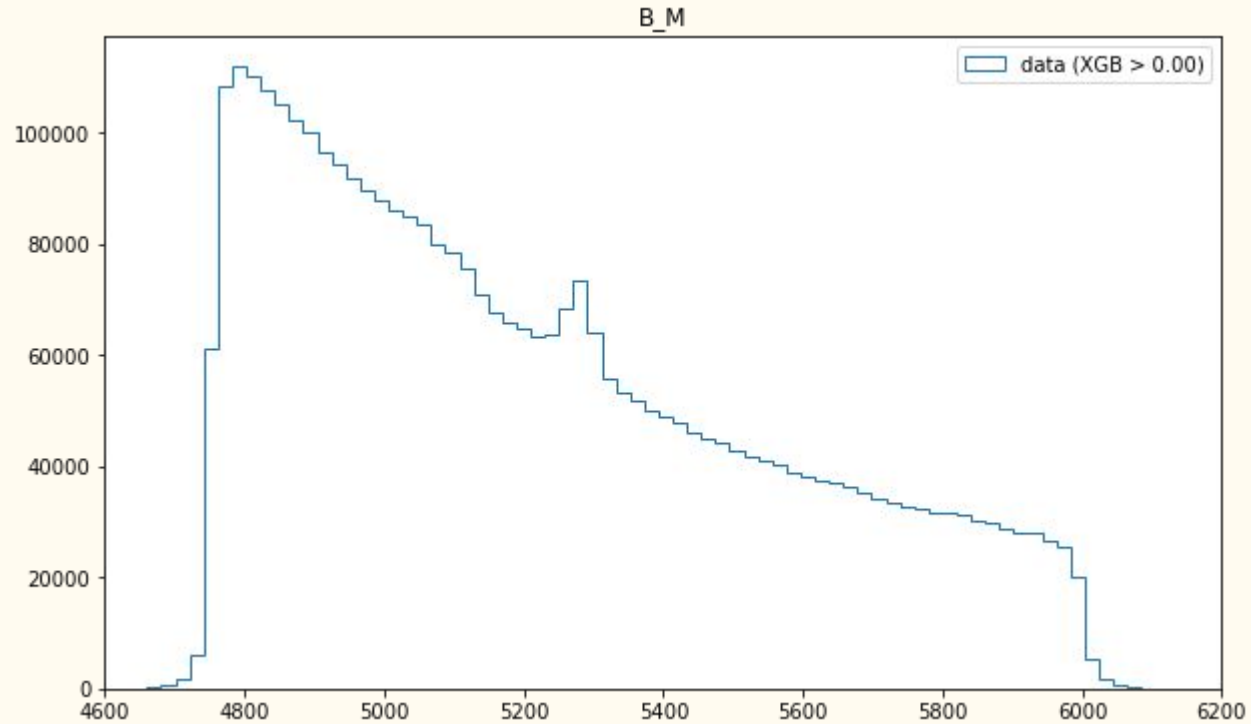
Plots for reference channel



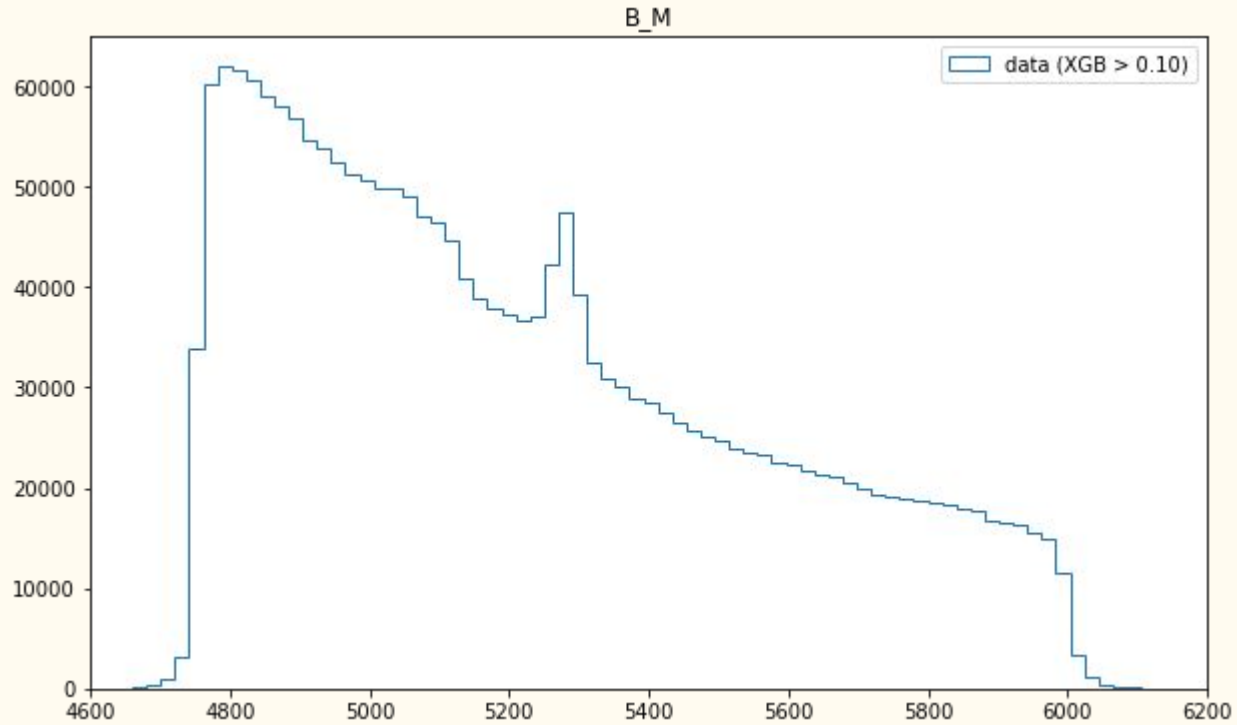
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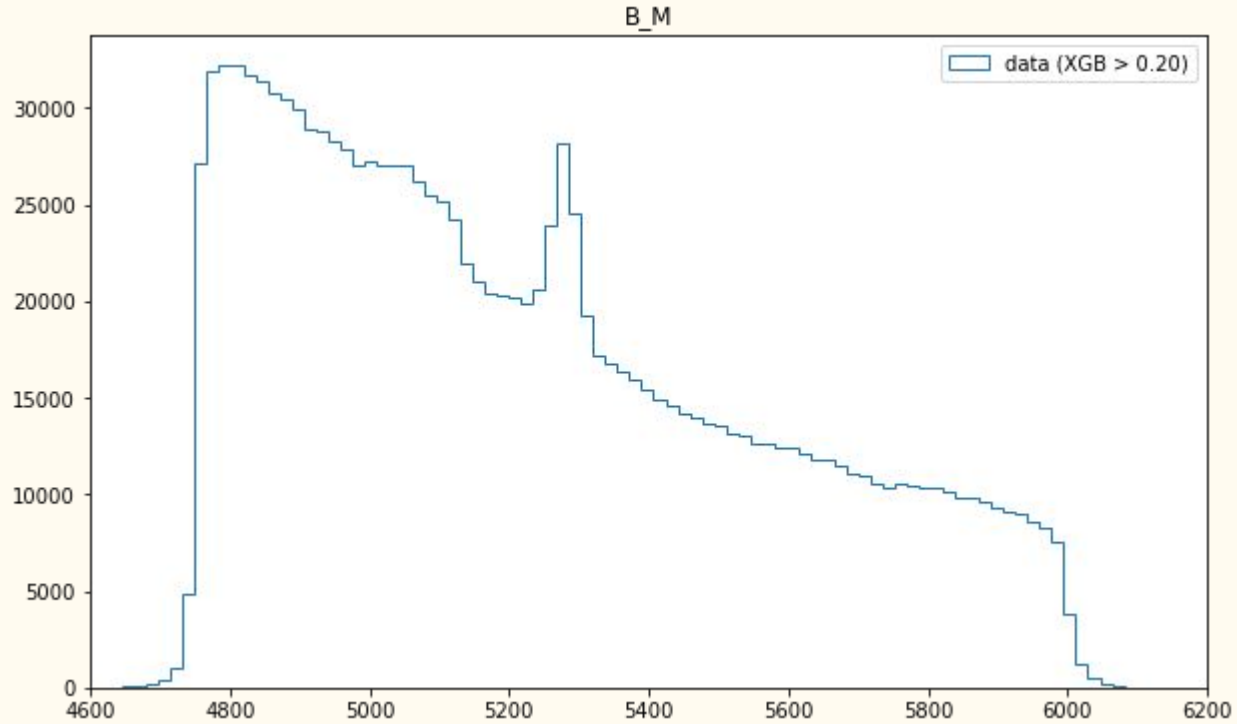
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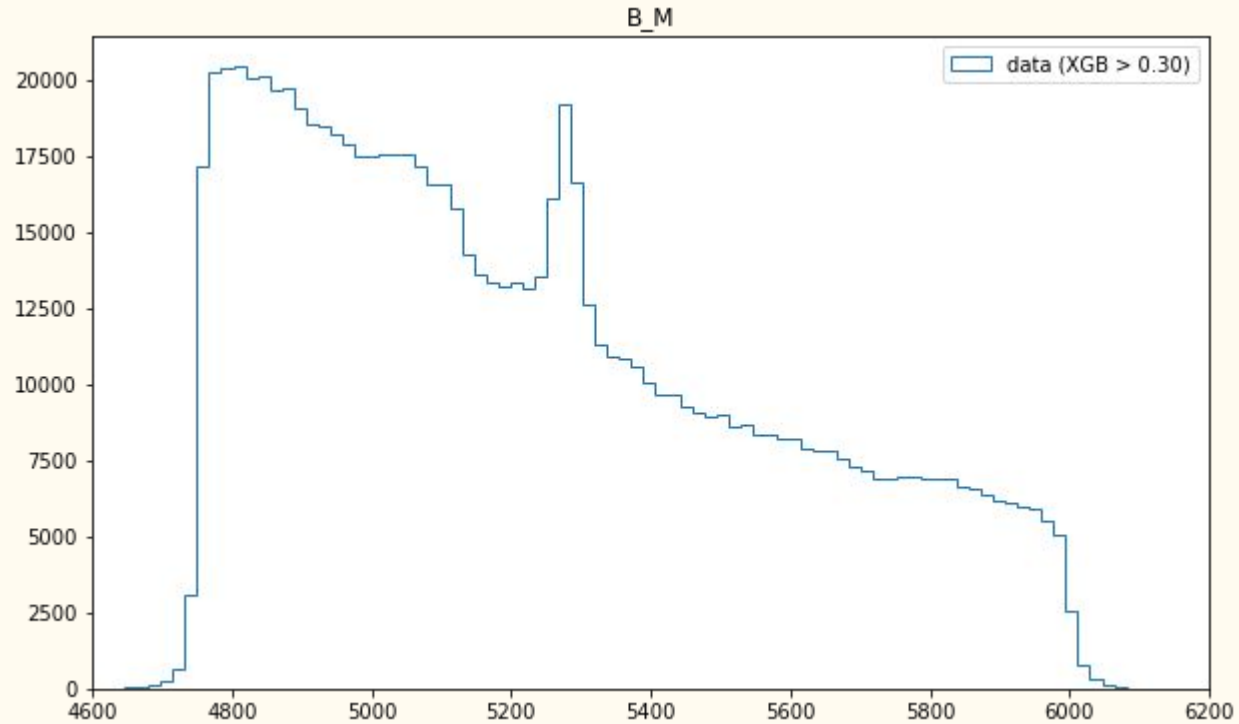
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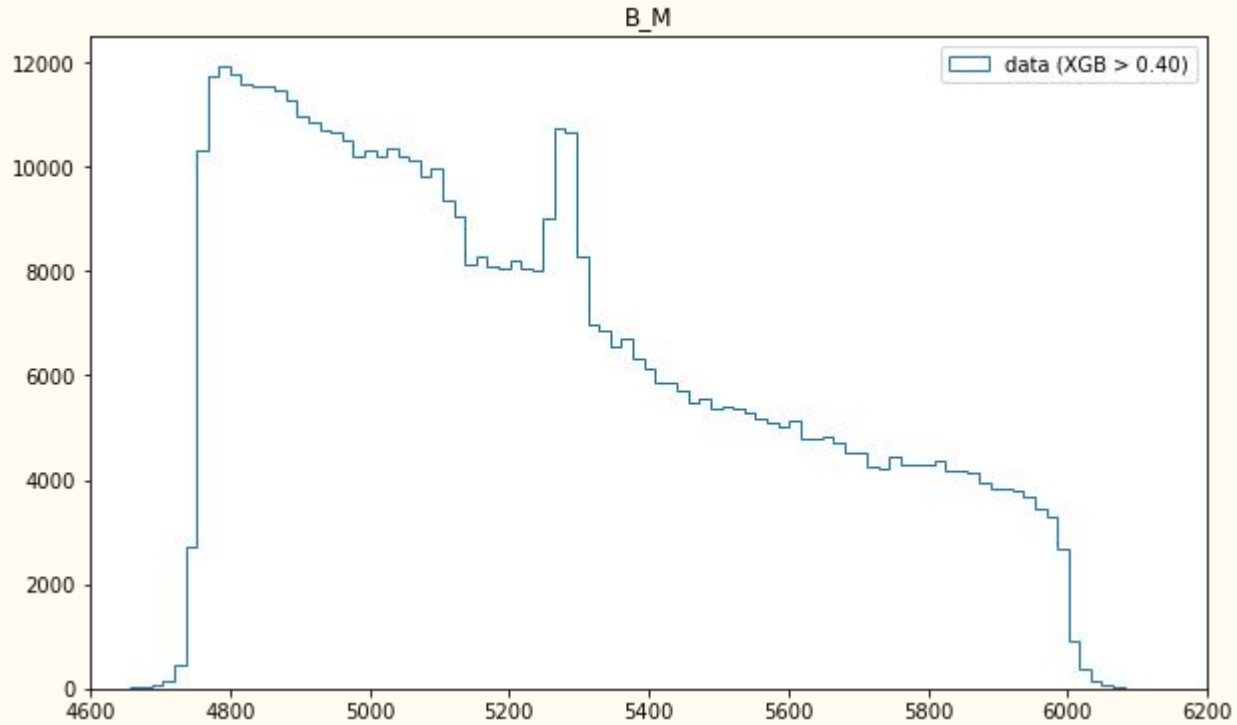
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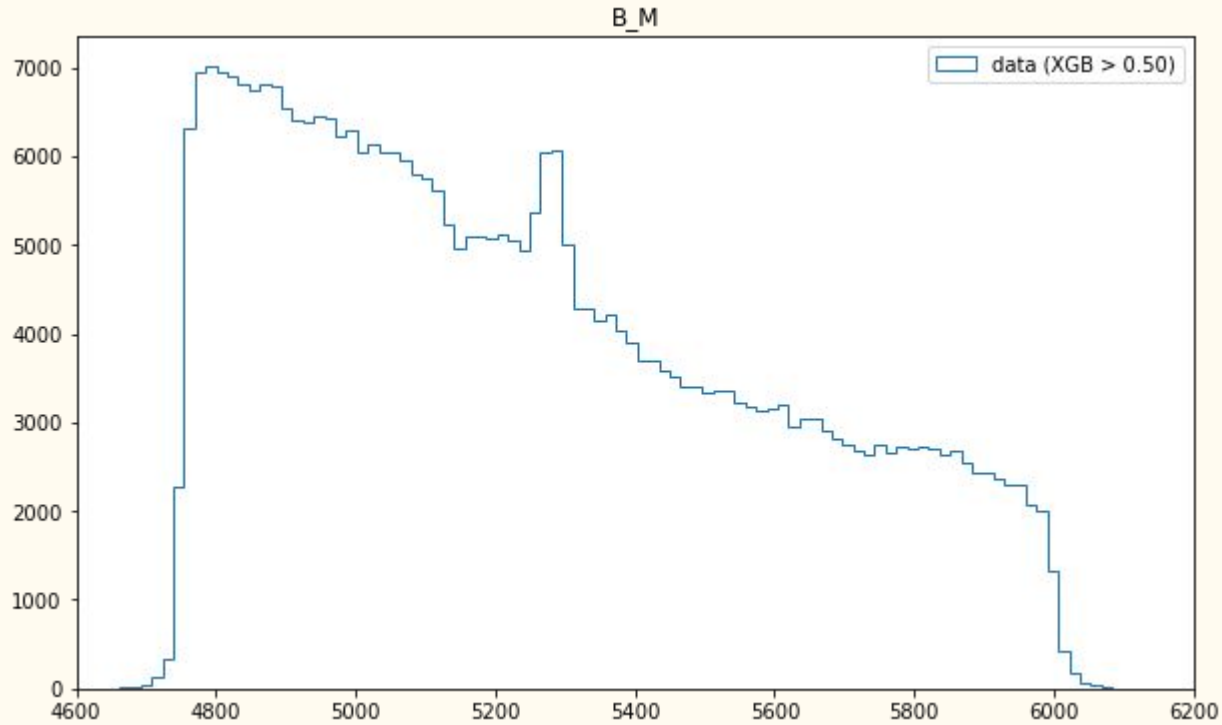
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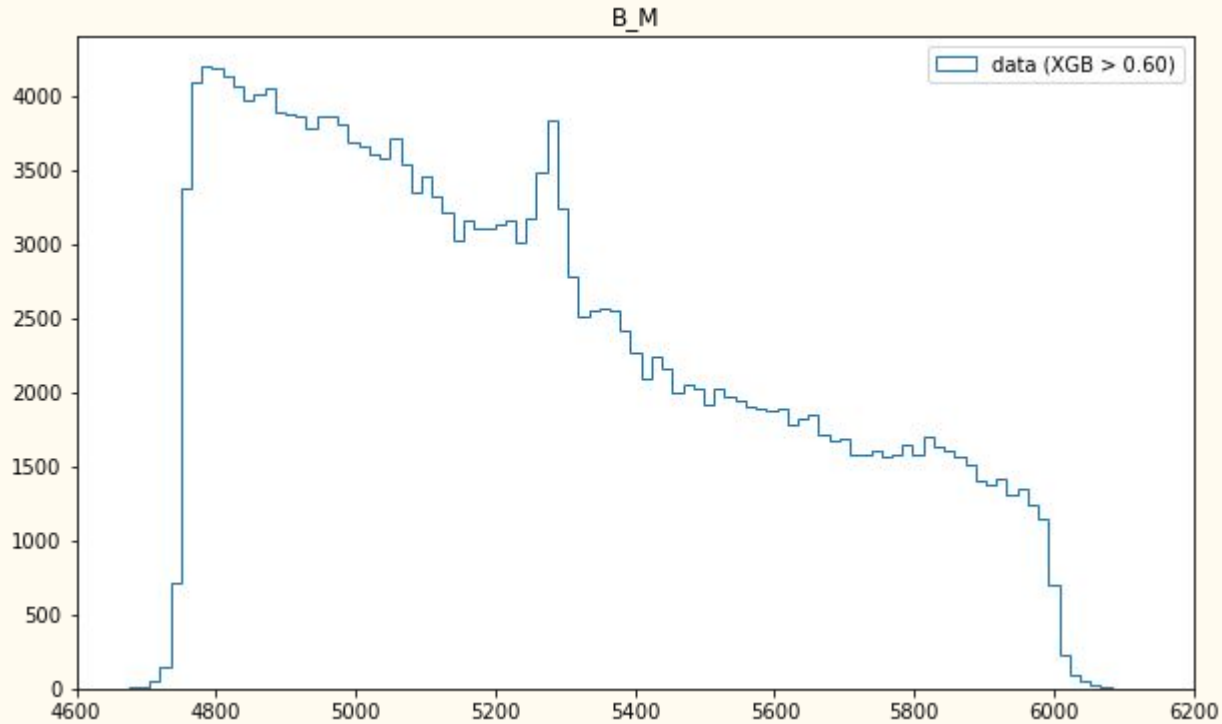
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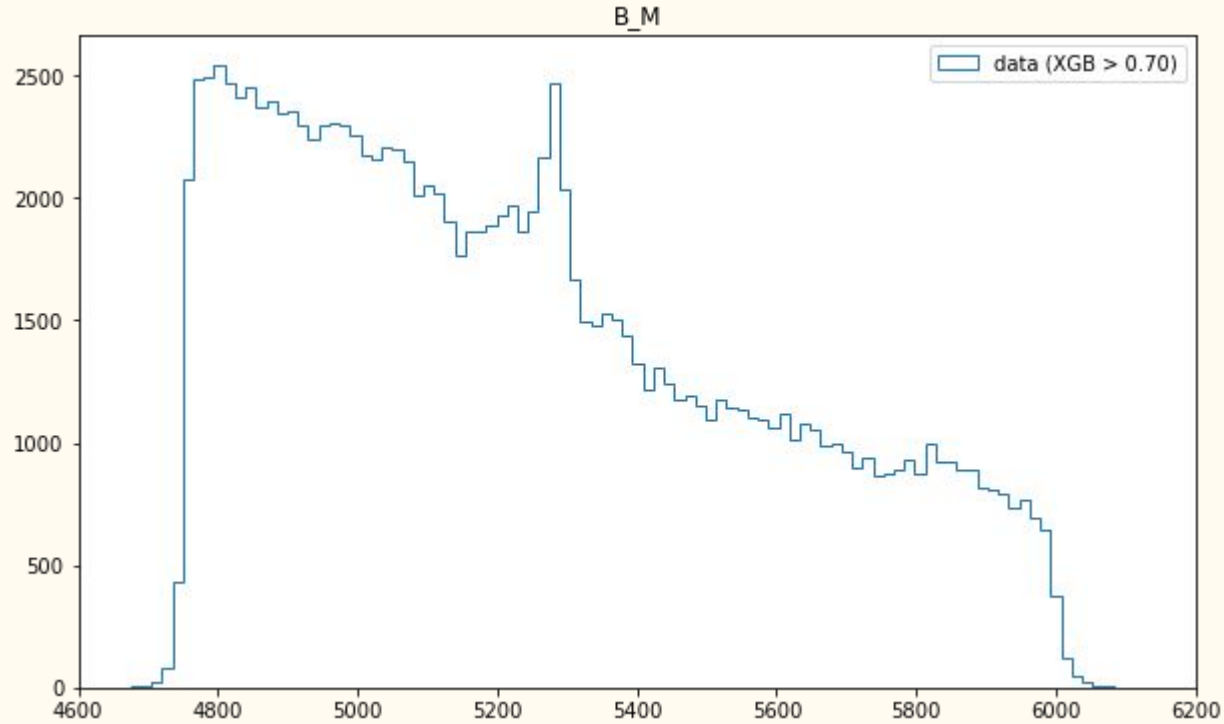
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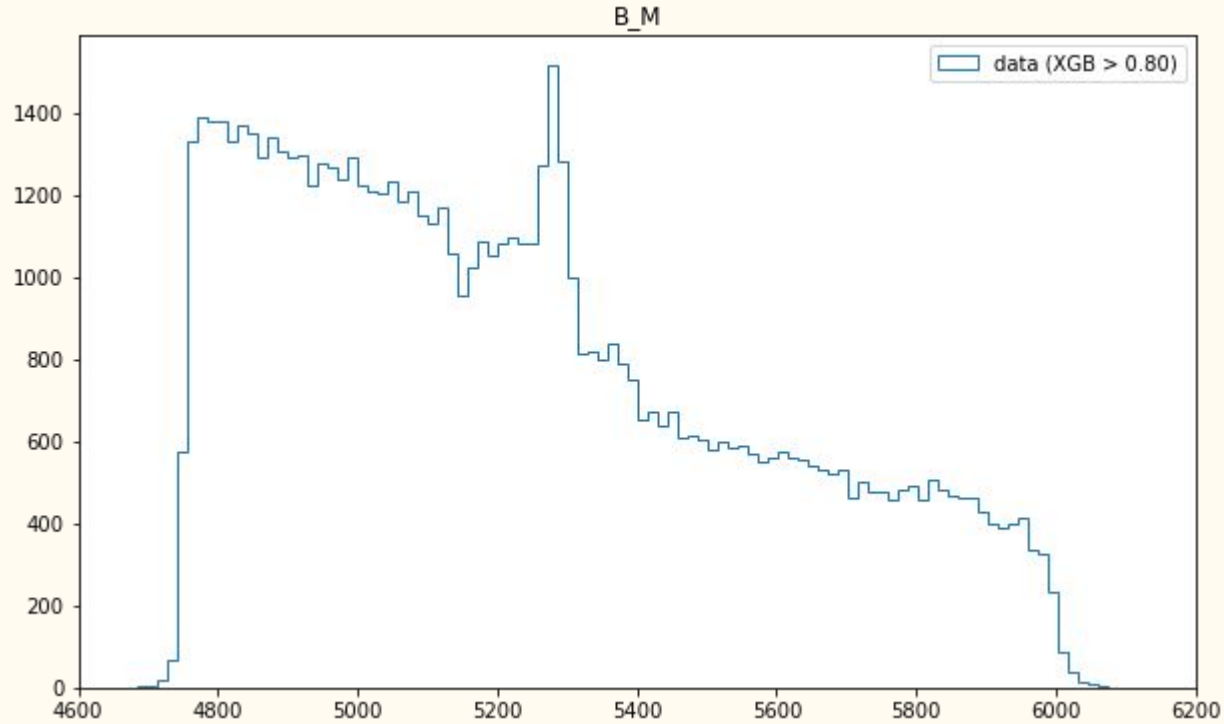
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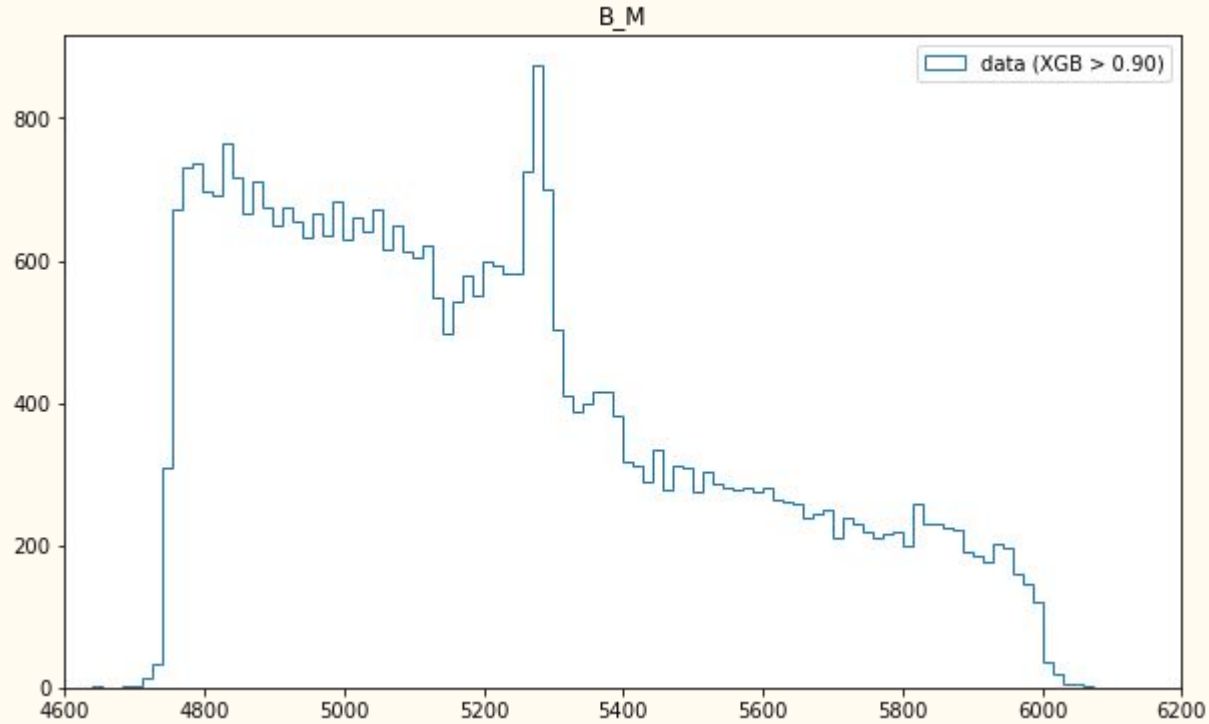
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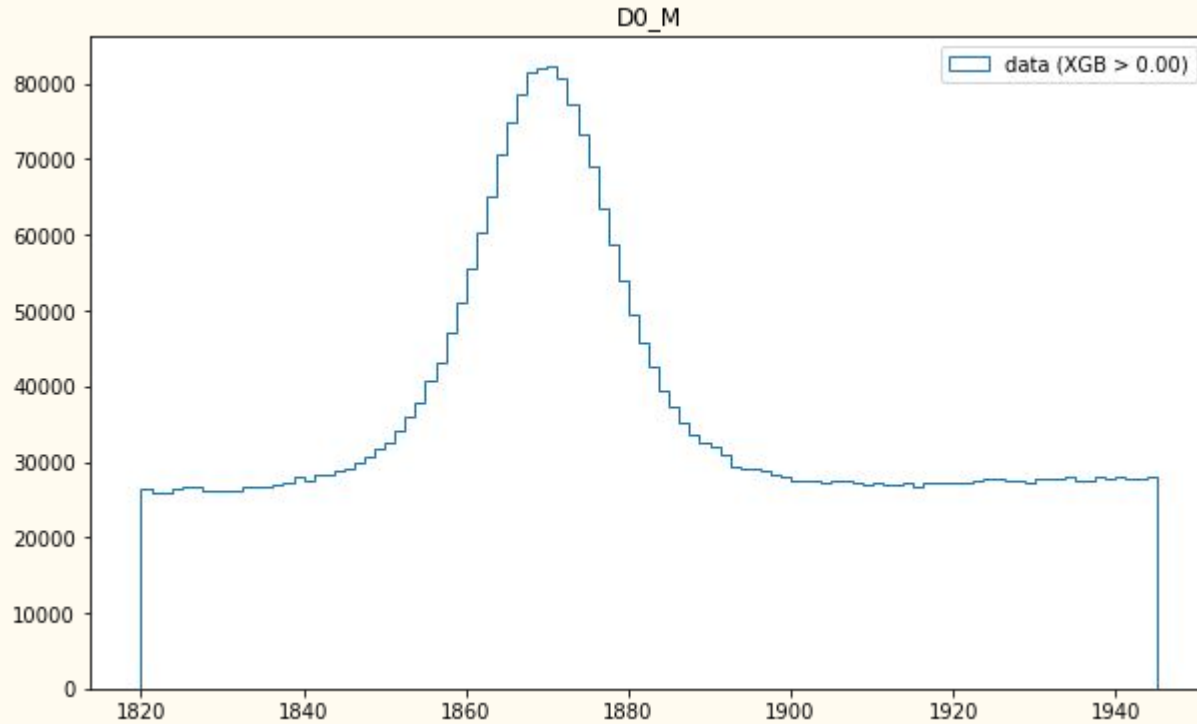
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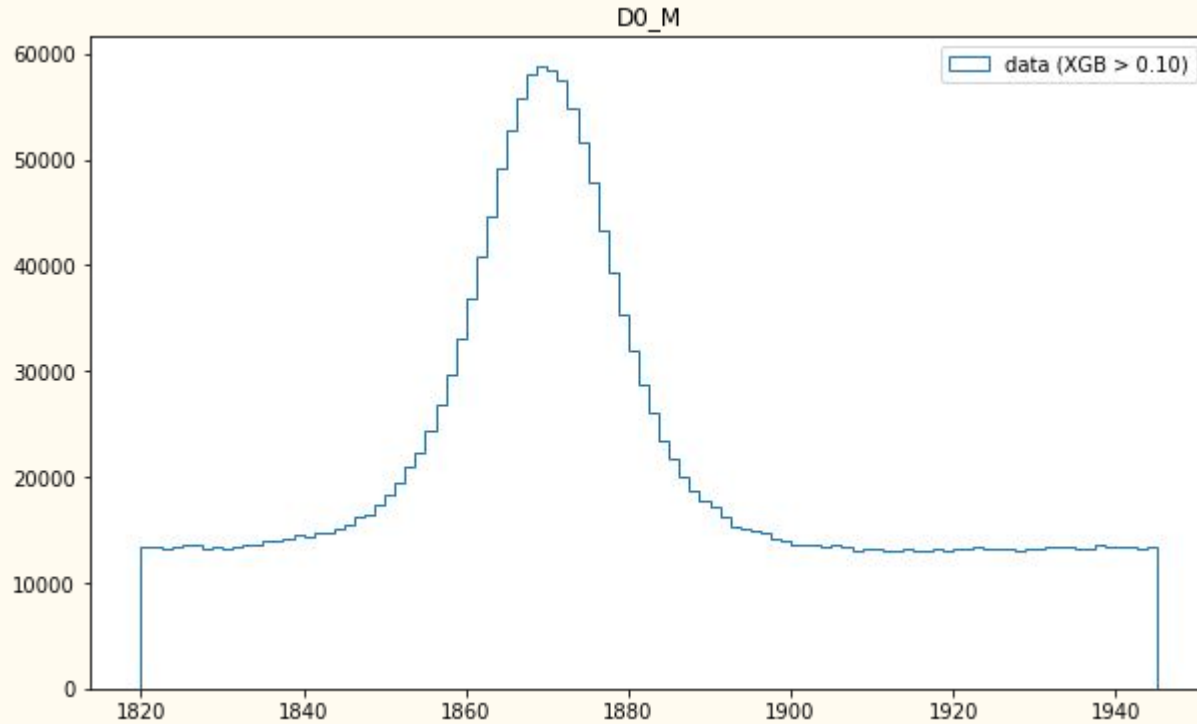
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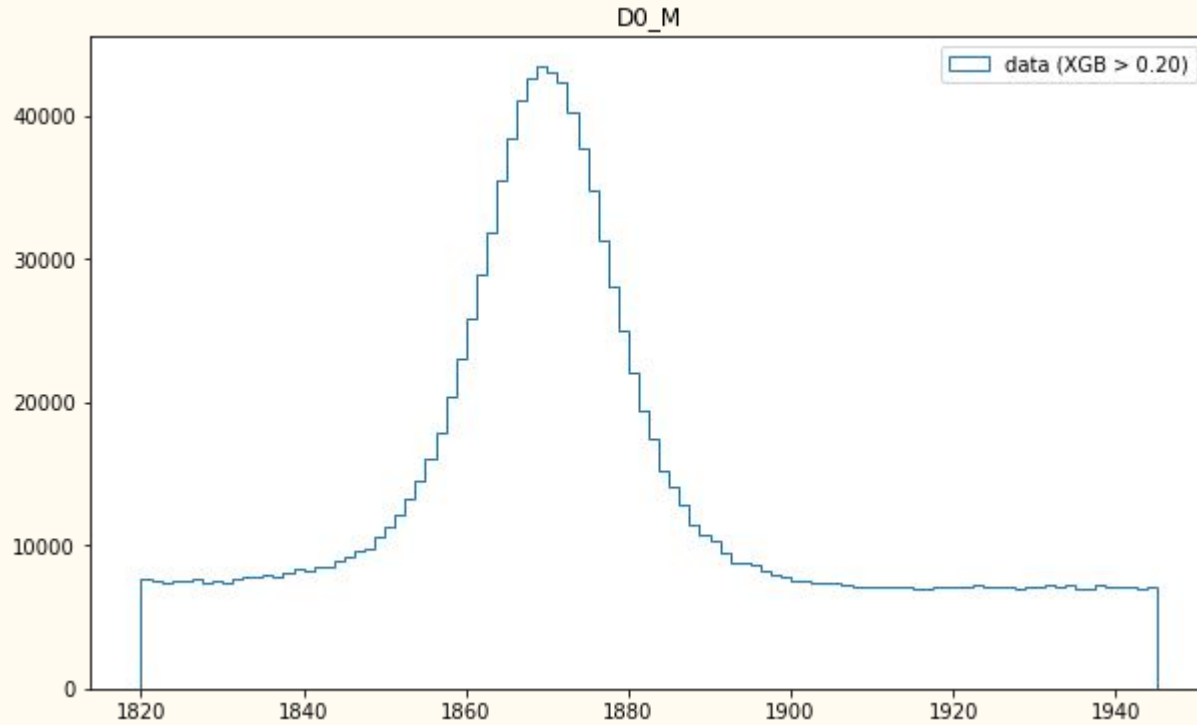
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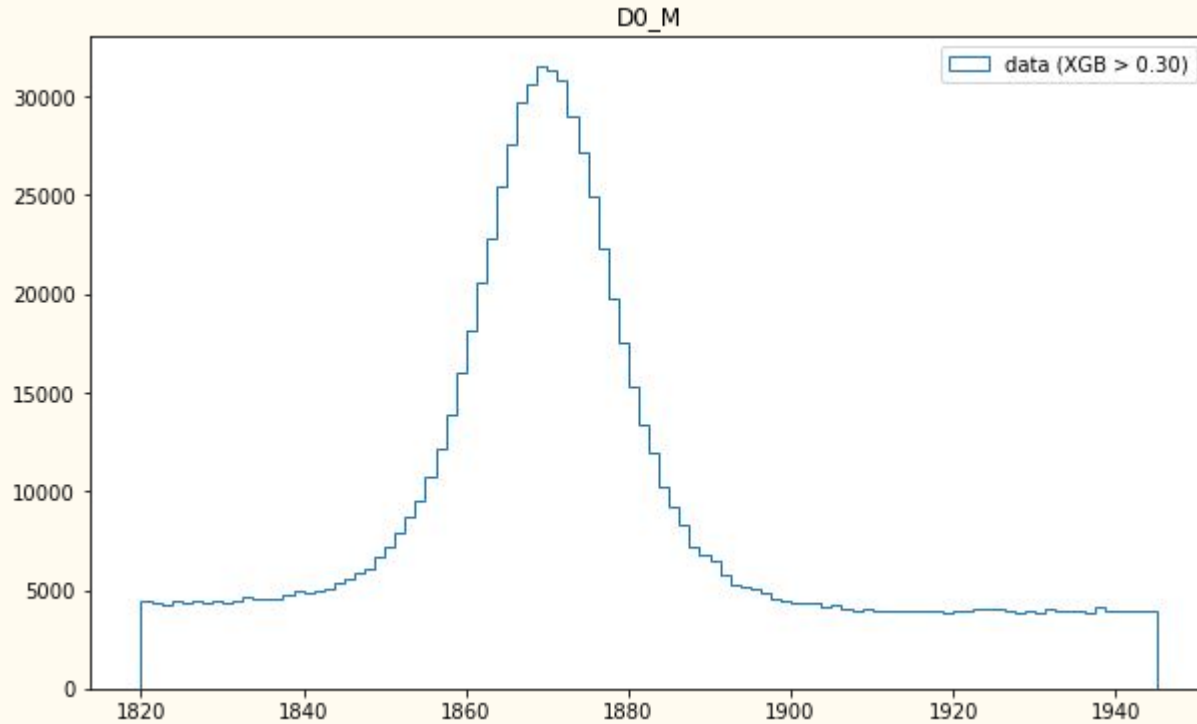
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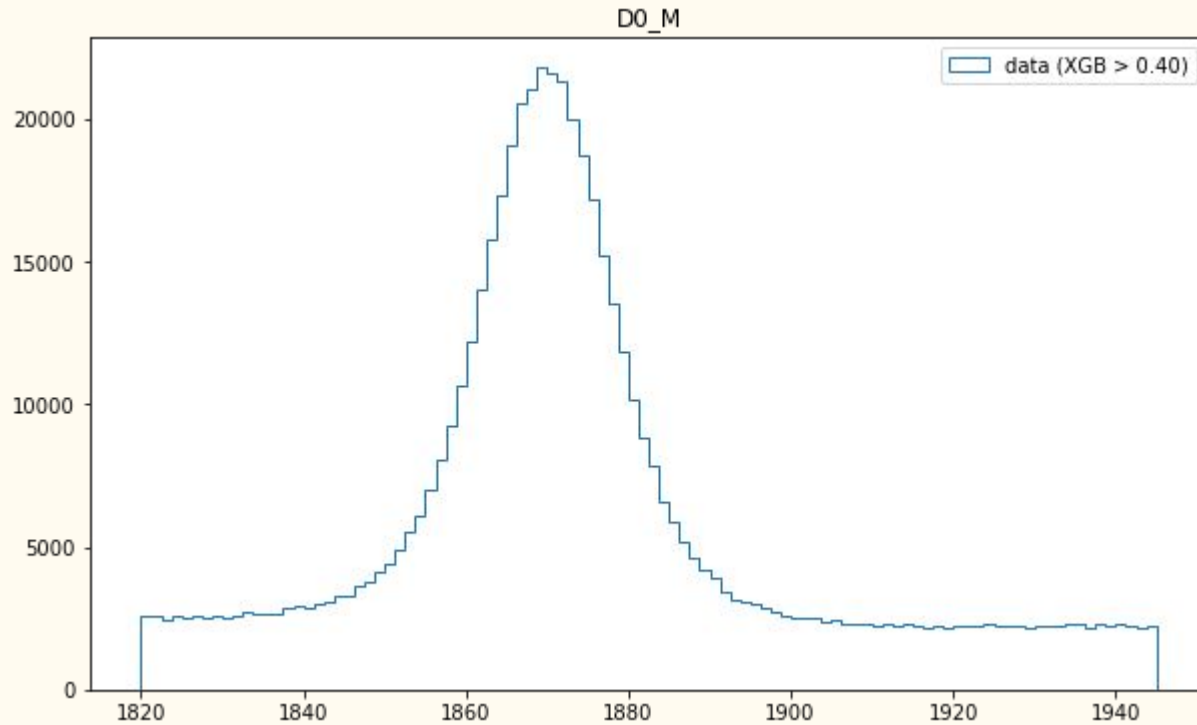
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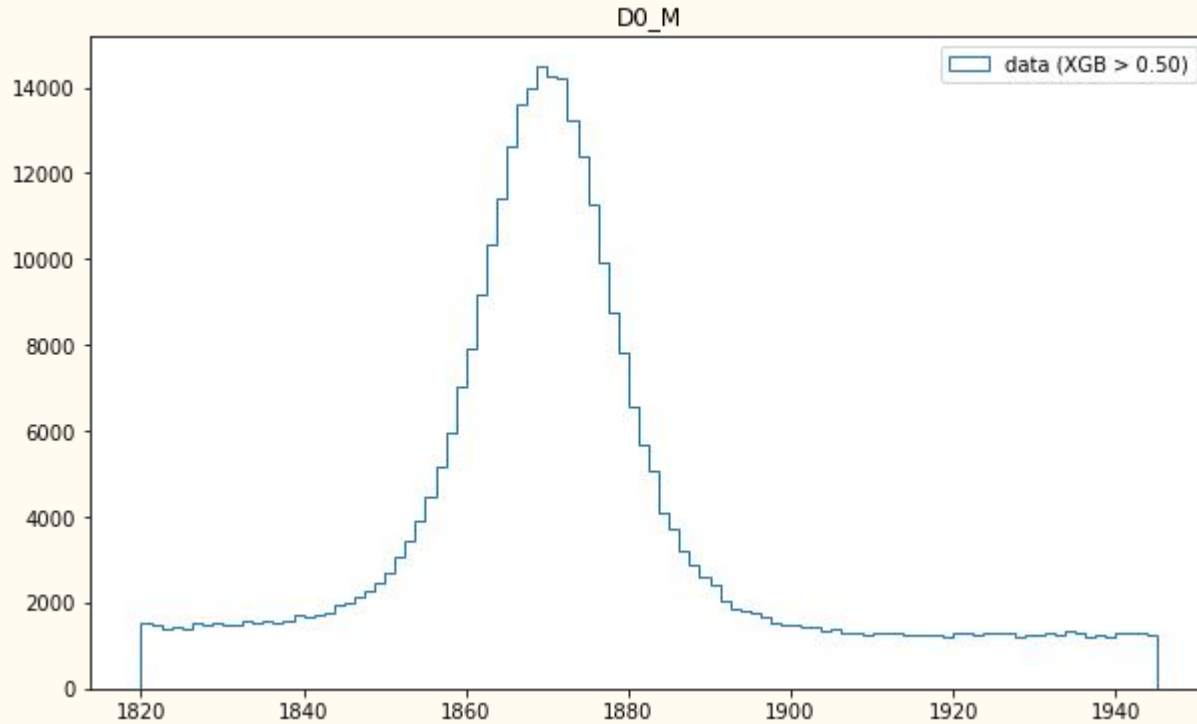
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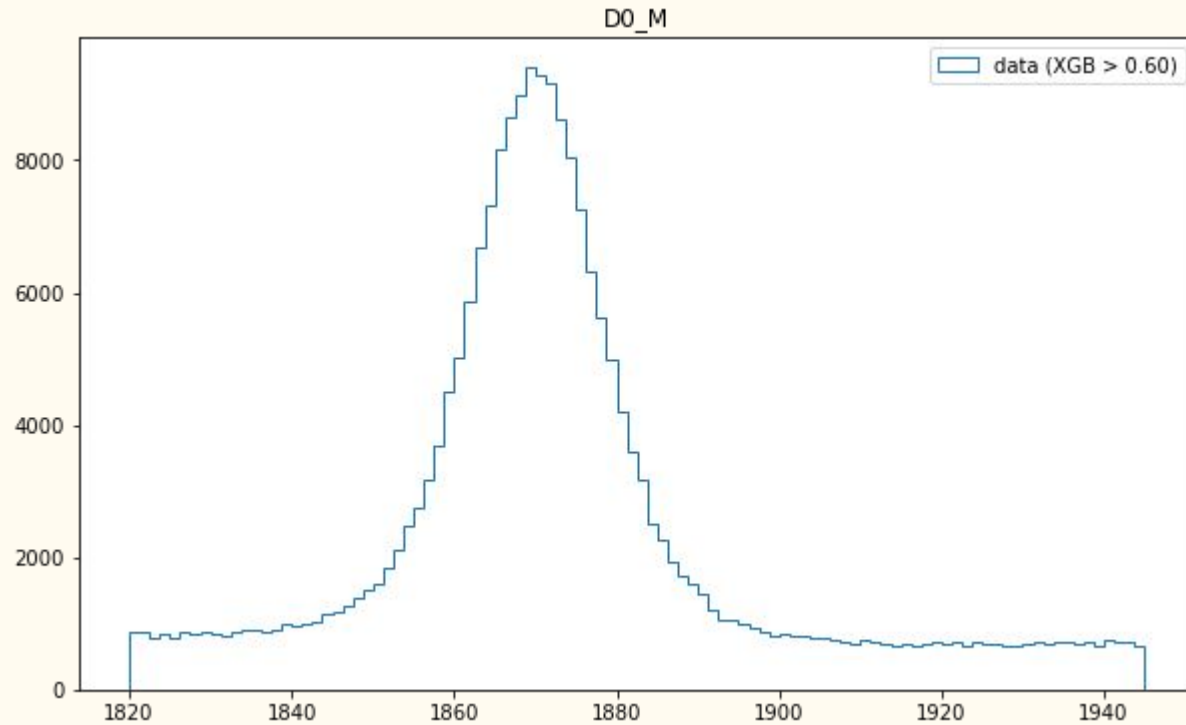
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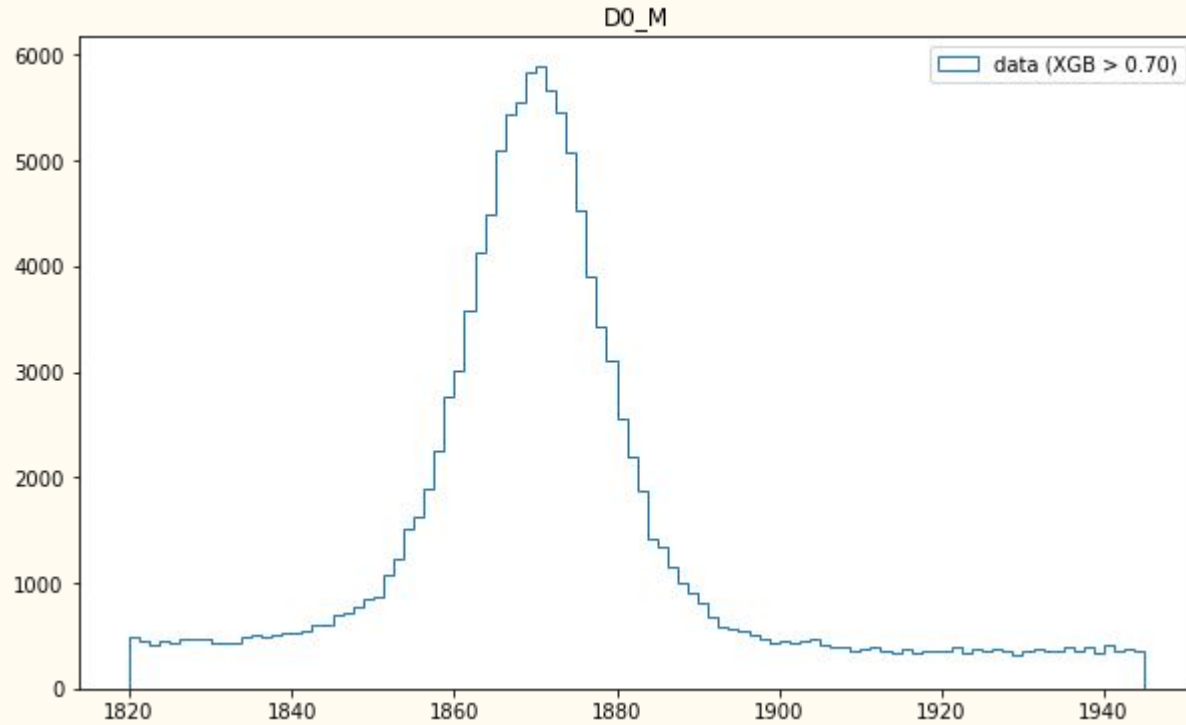
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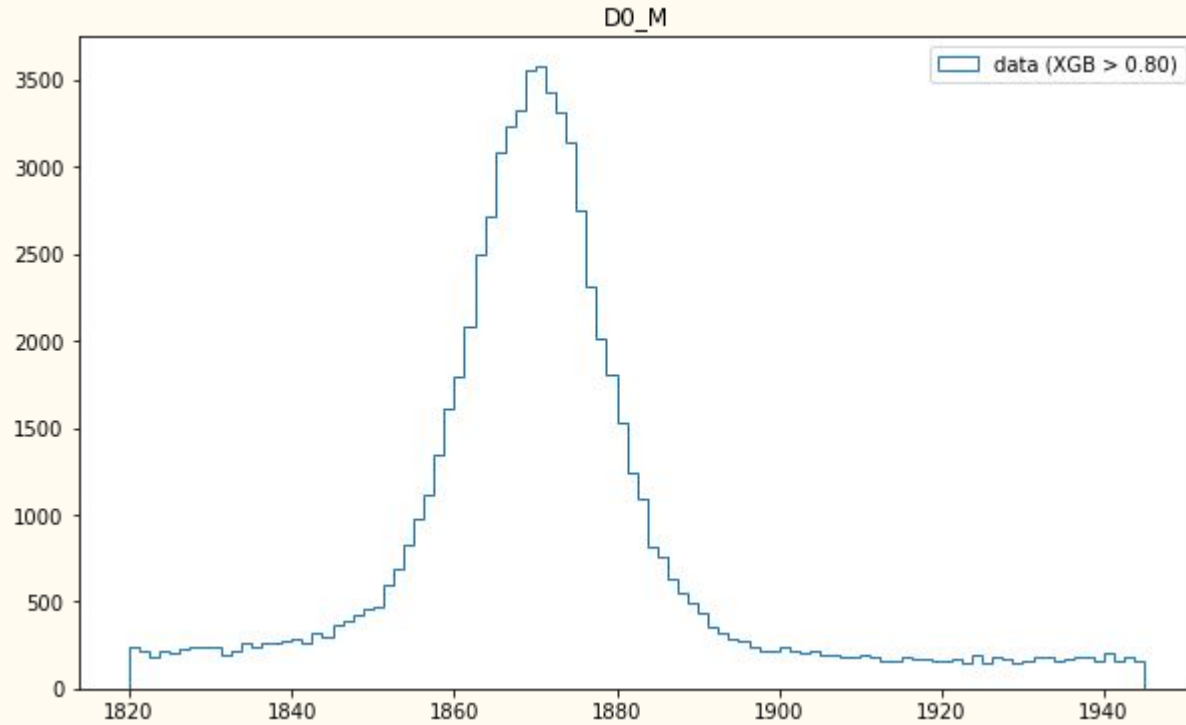
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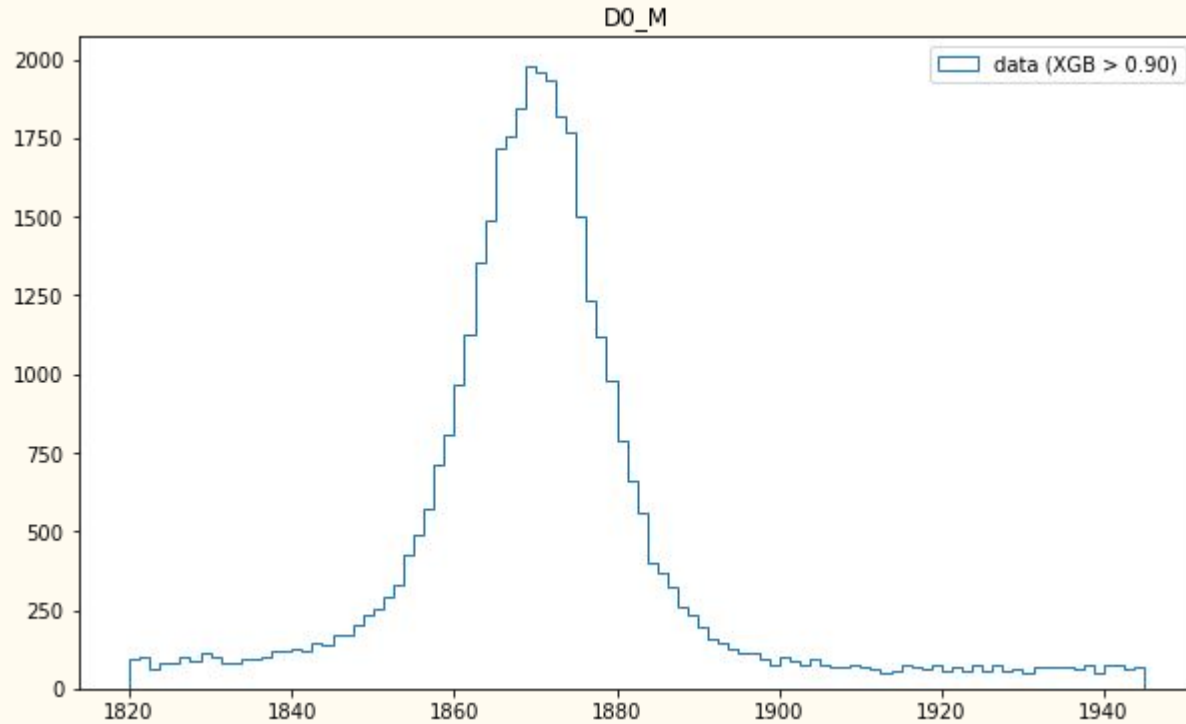
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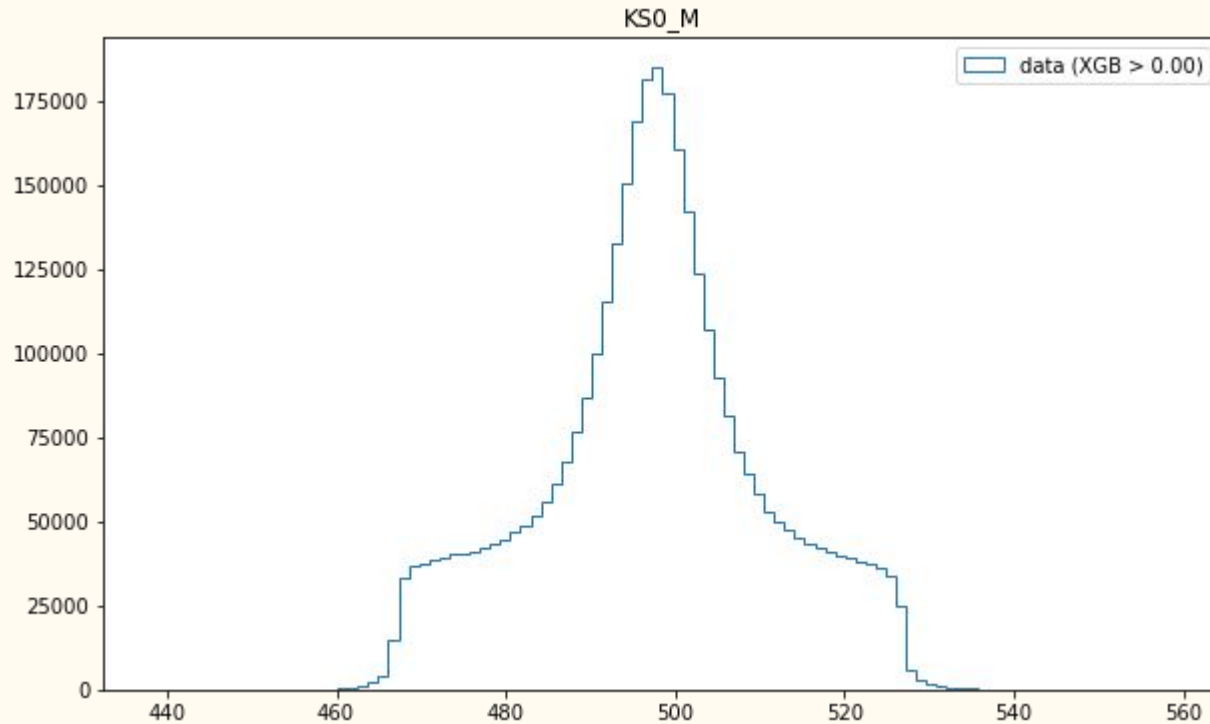
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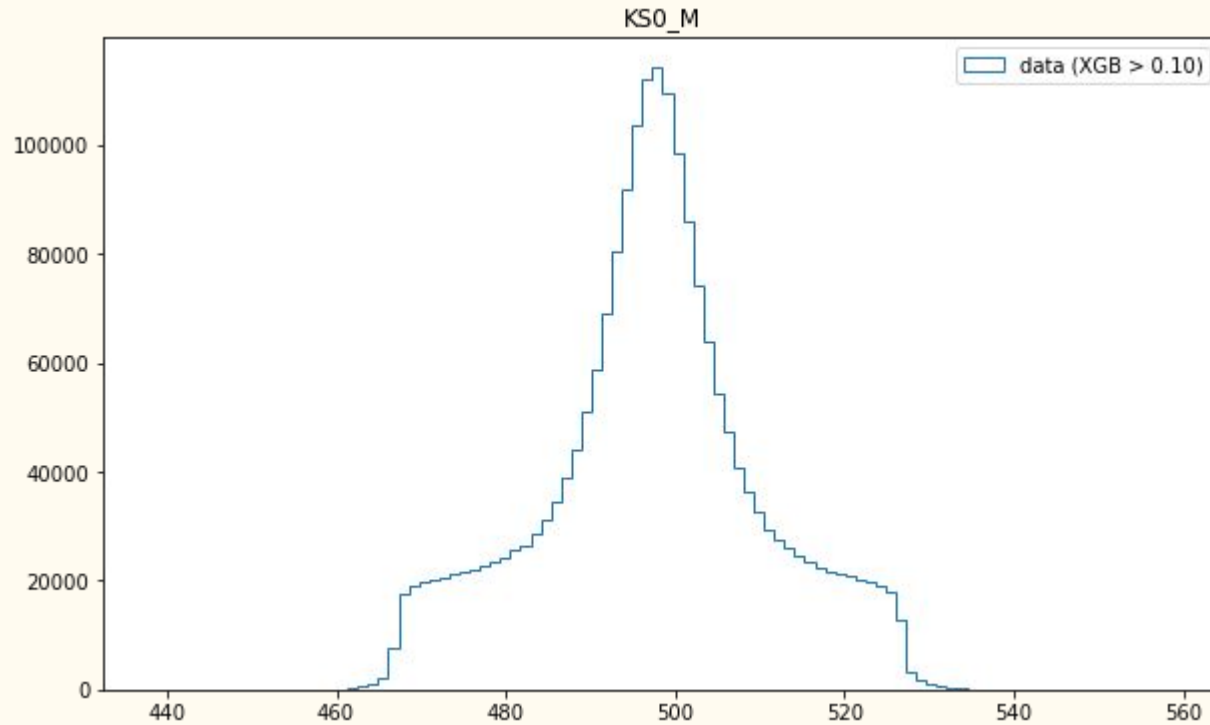
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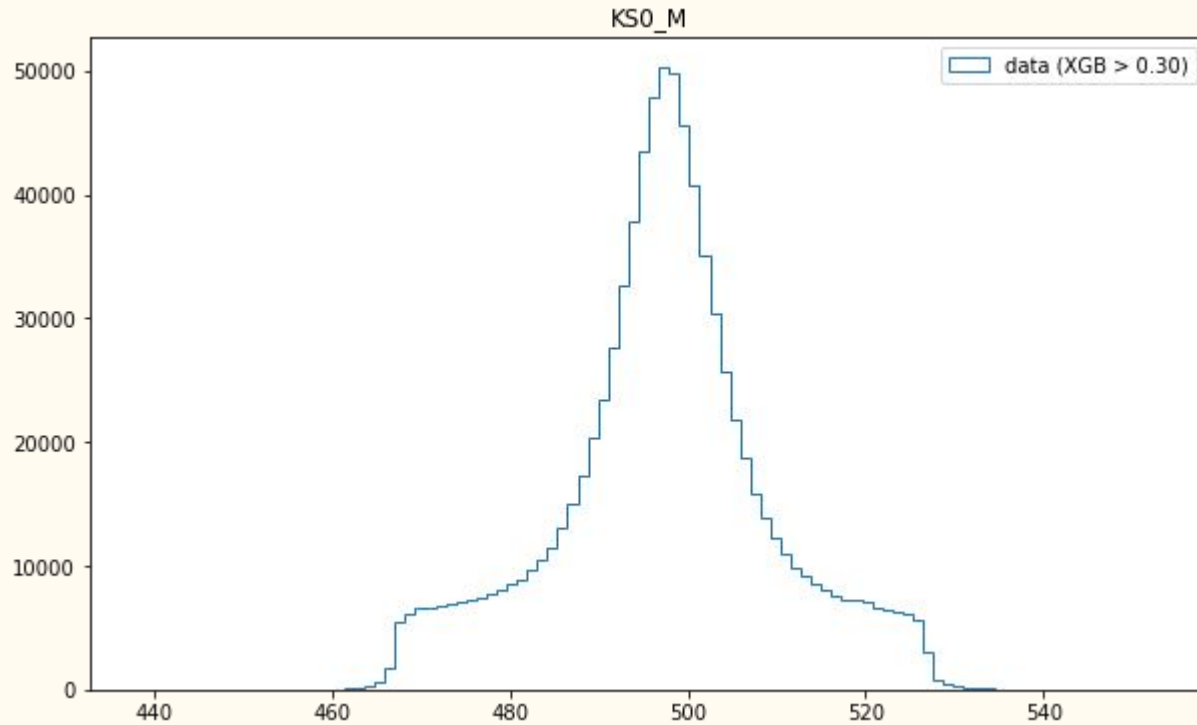
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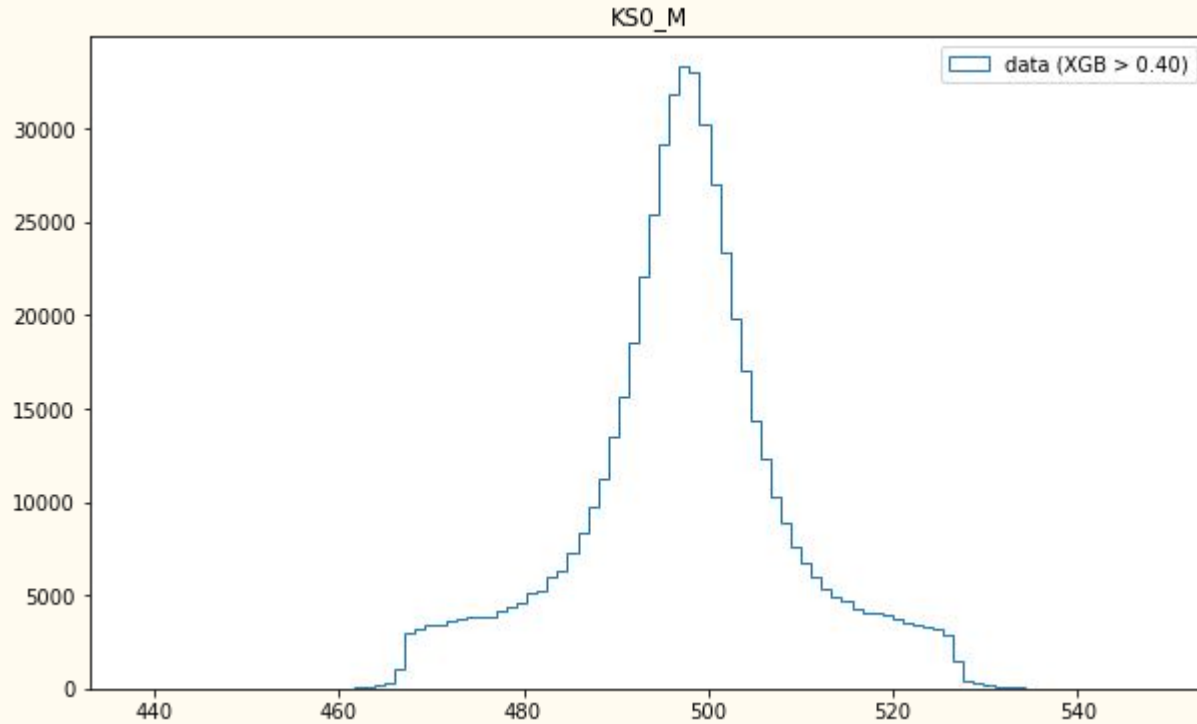
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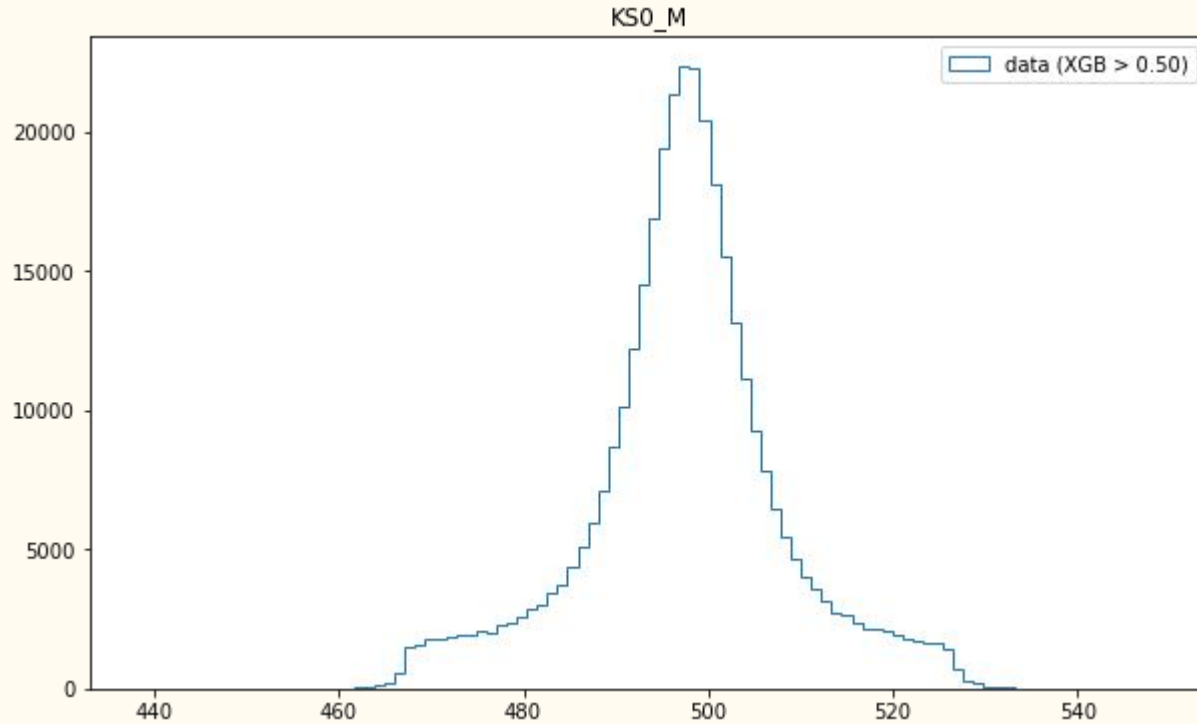
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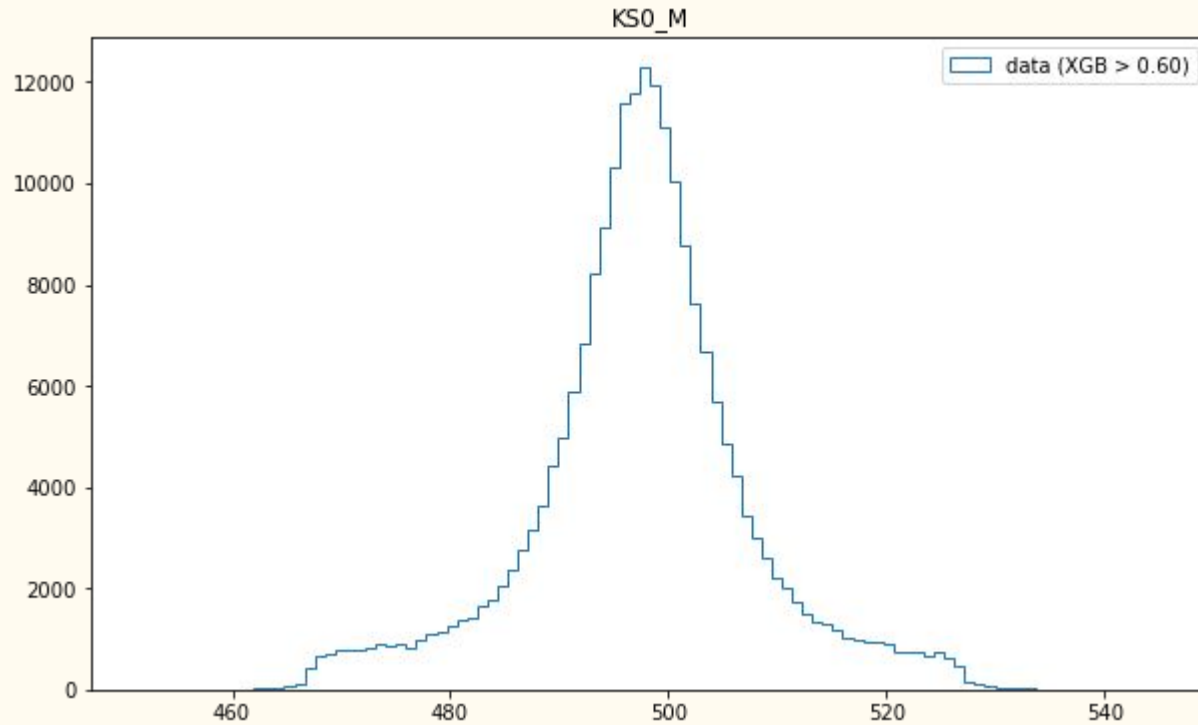
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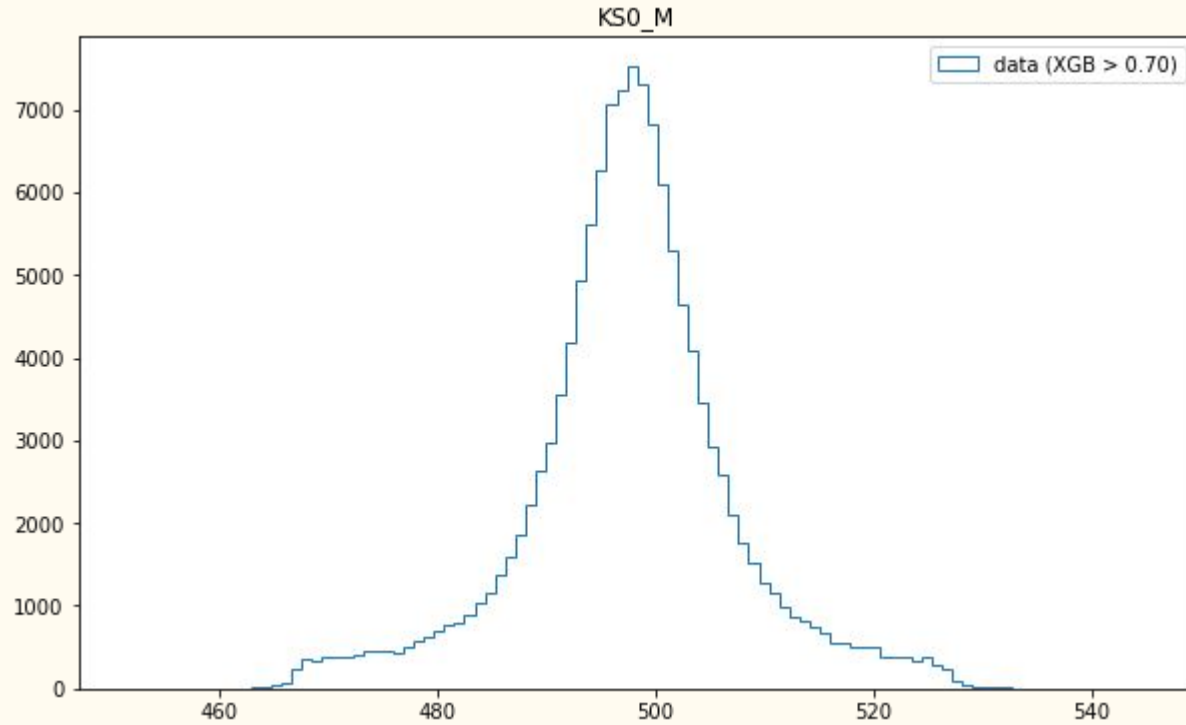
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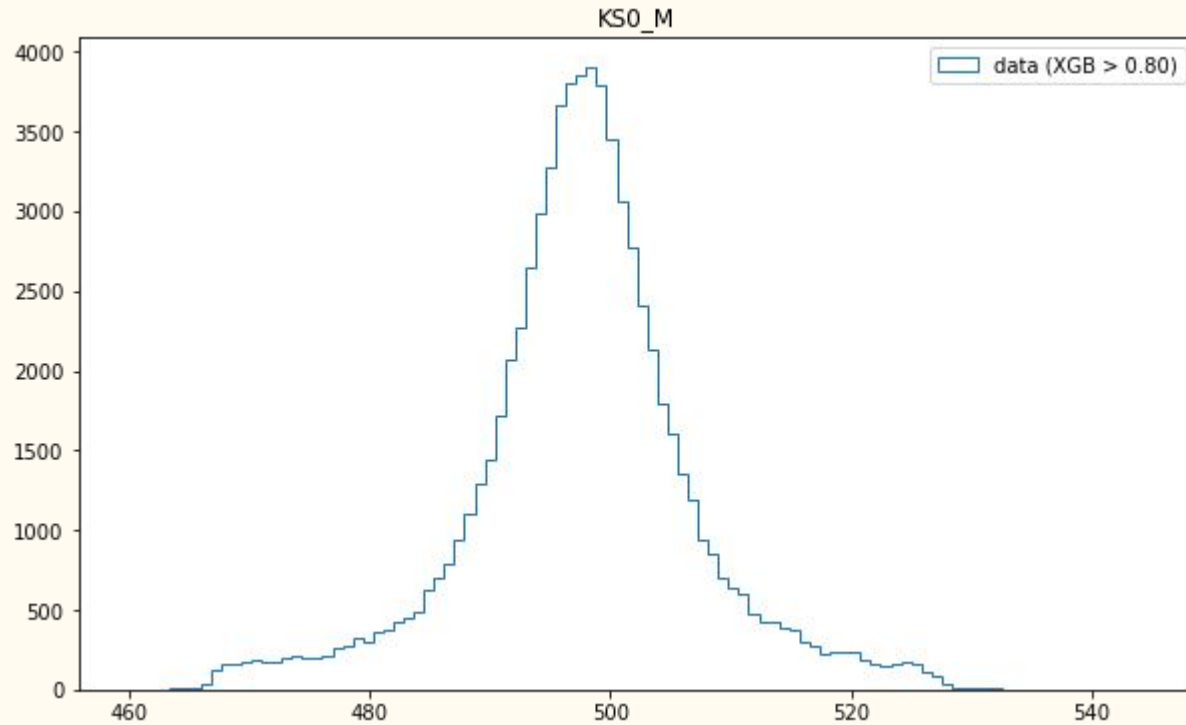
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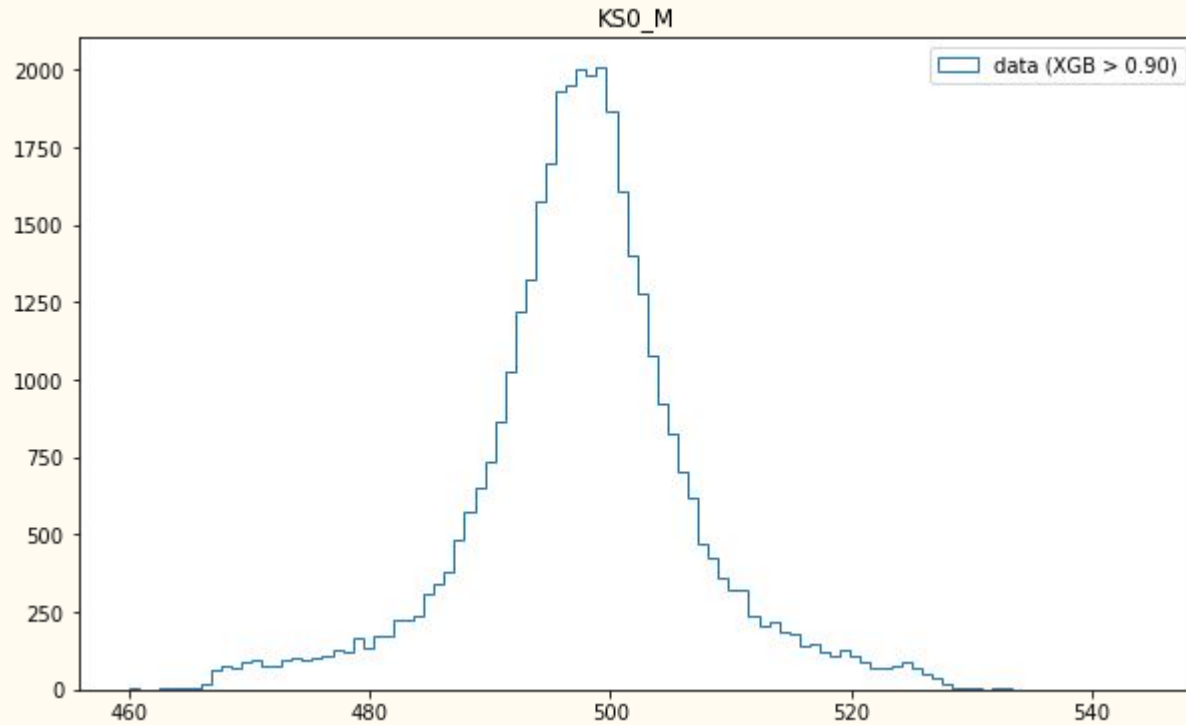
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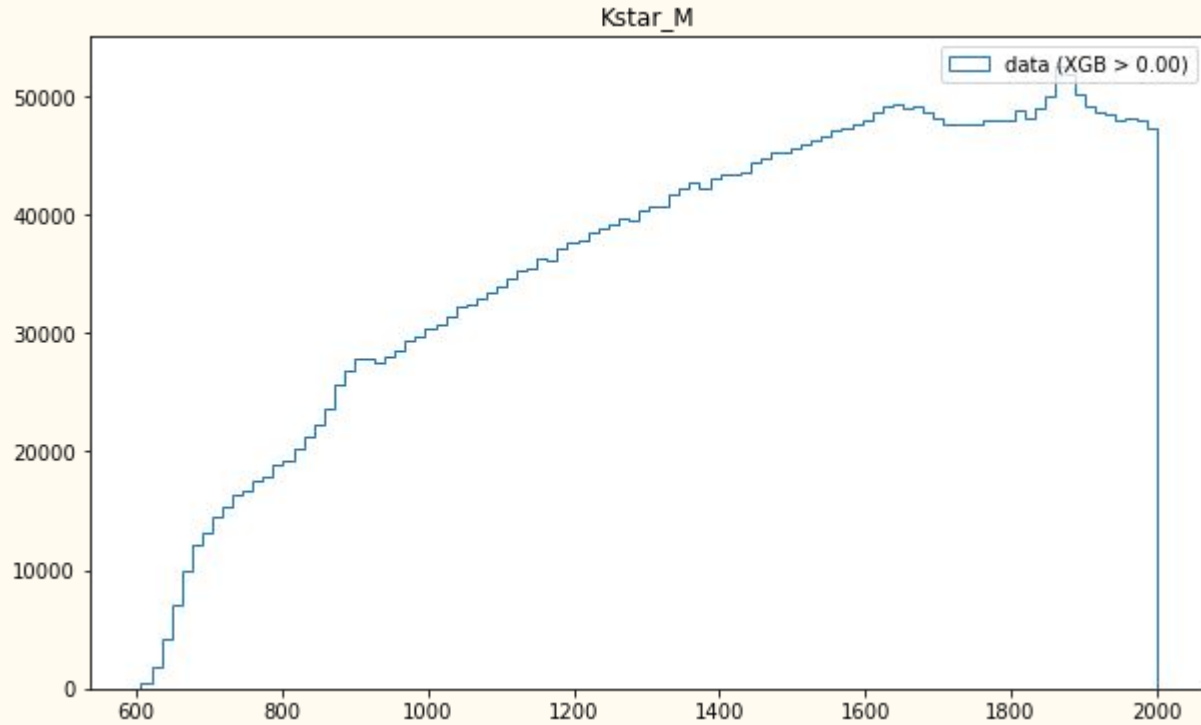
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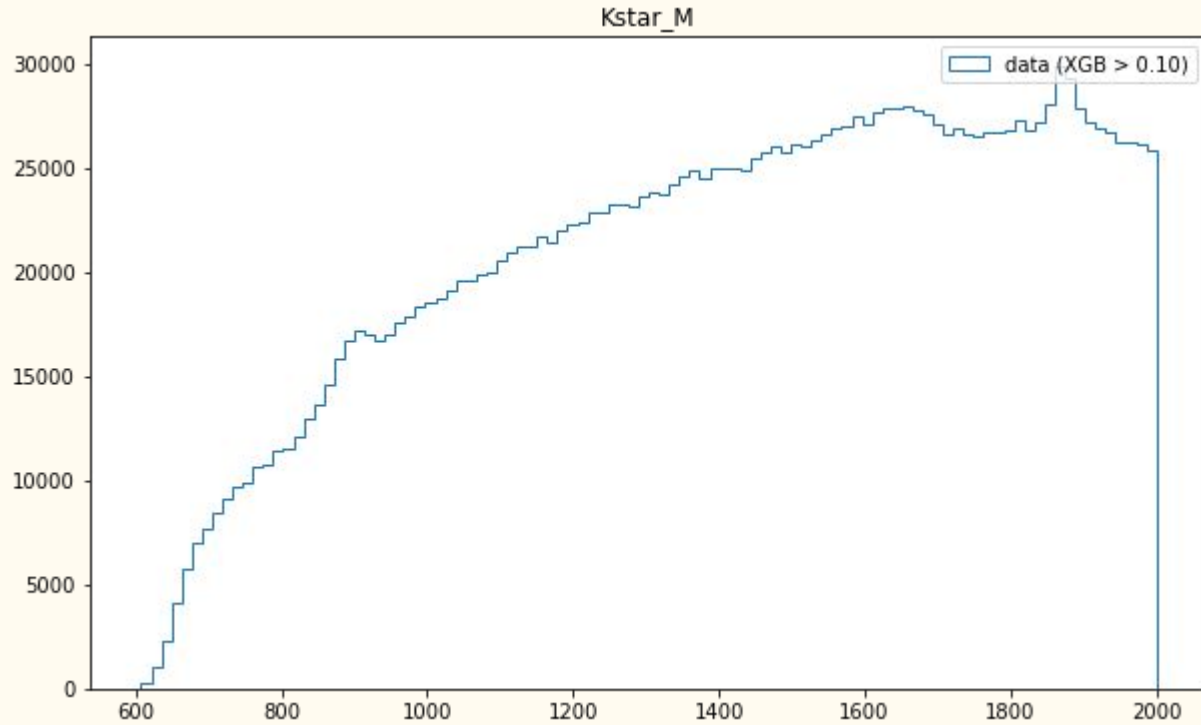
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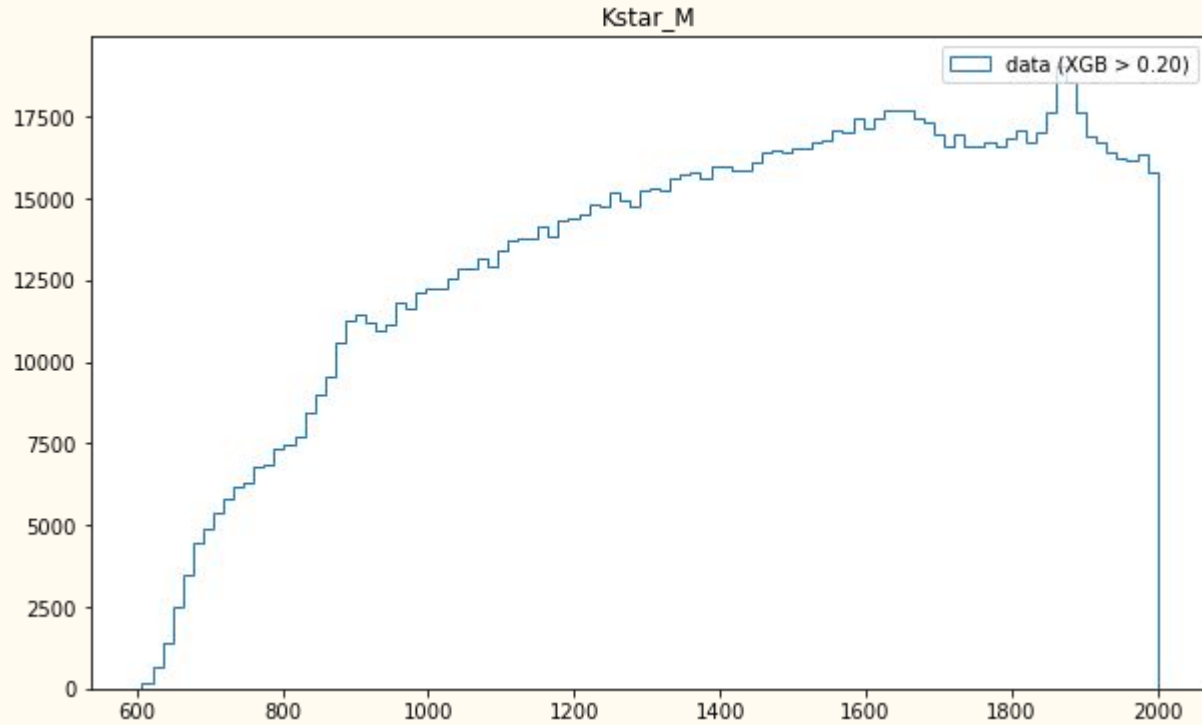
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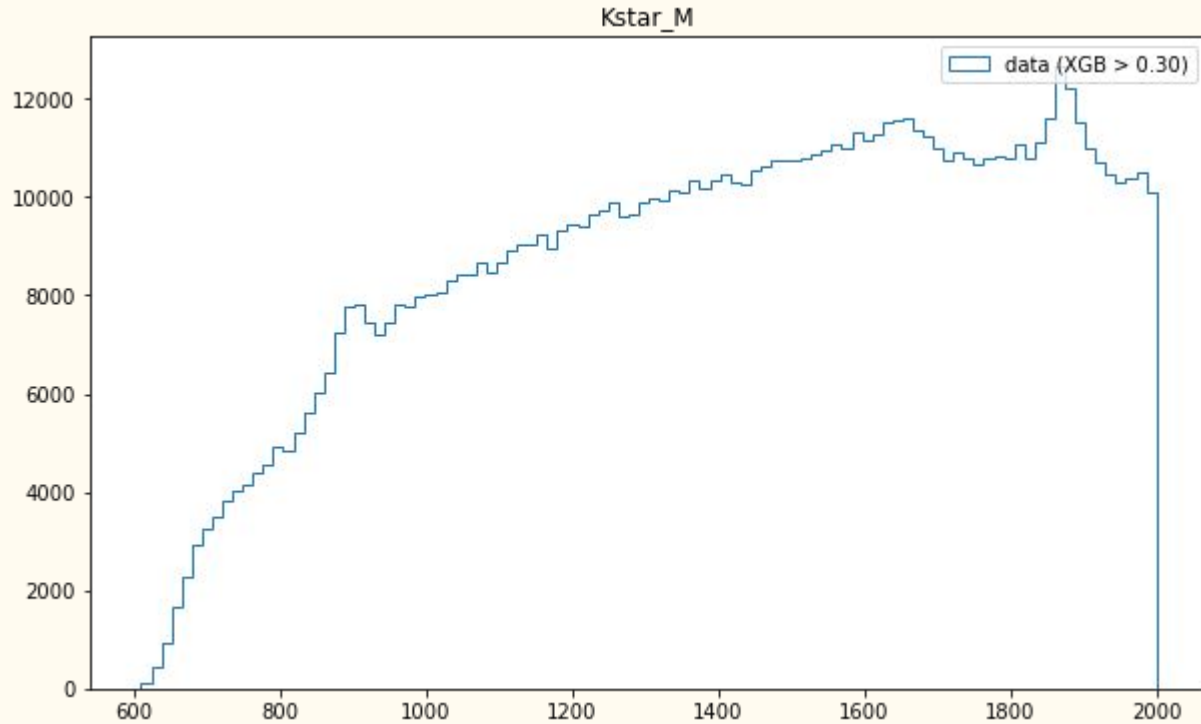
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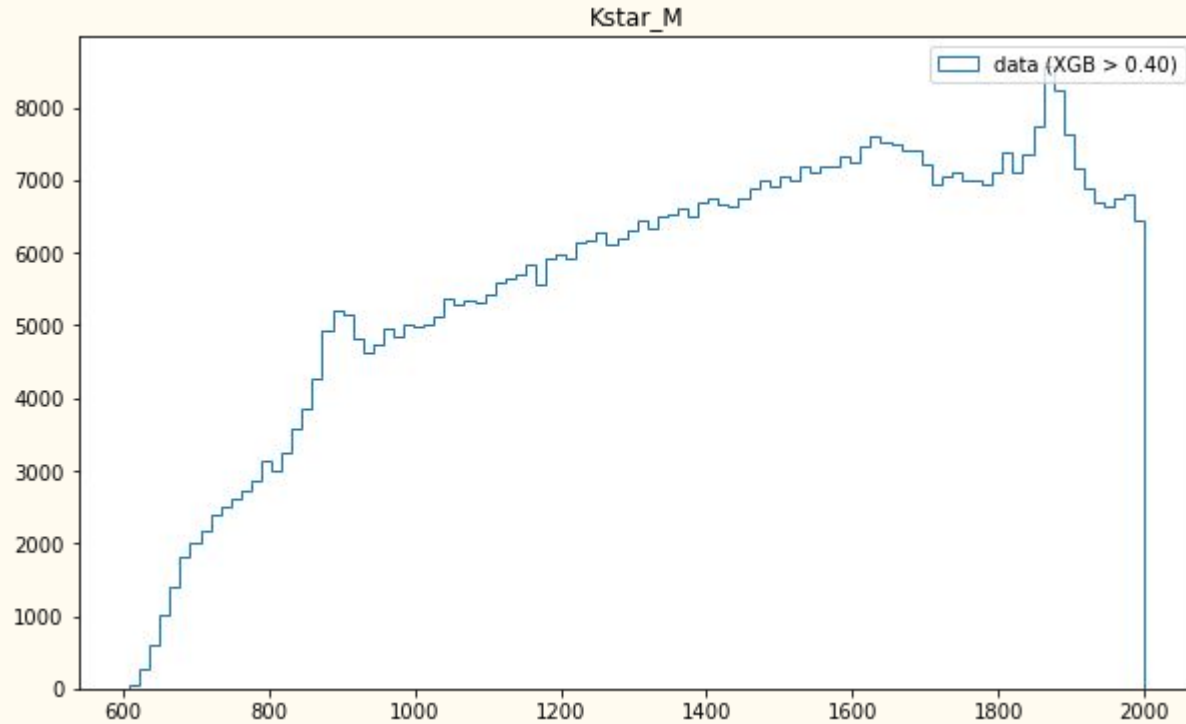
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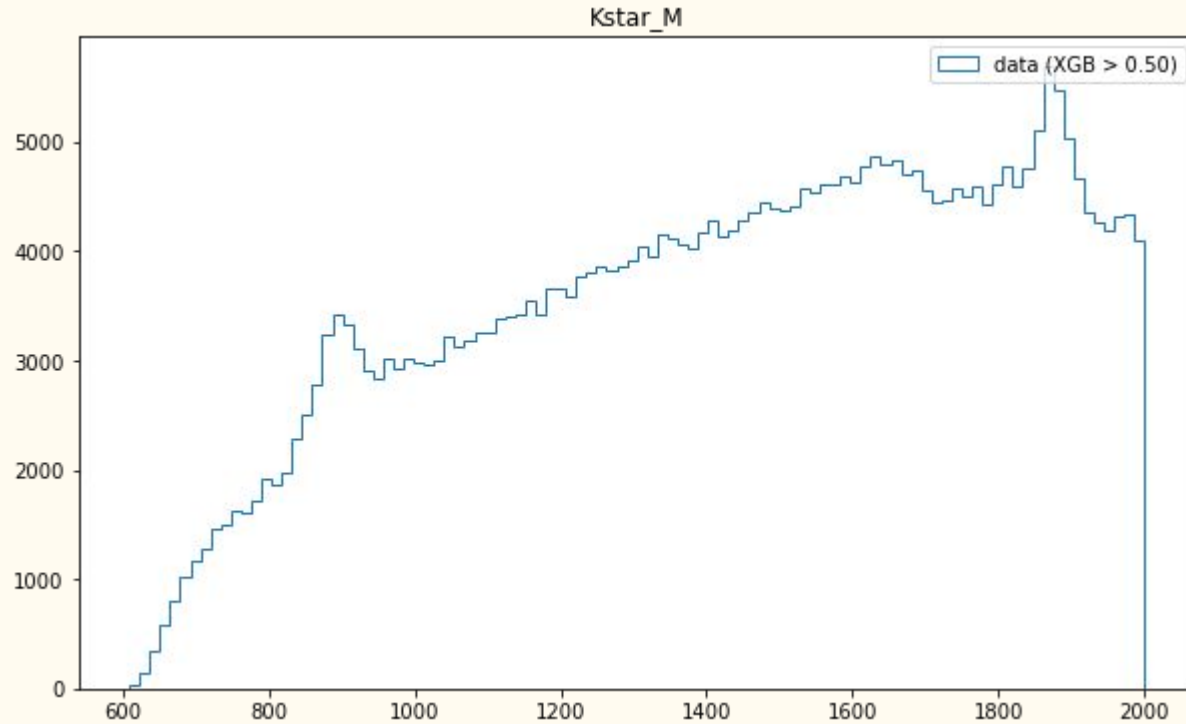
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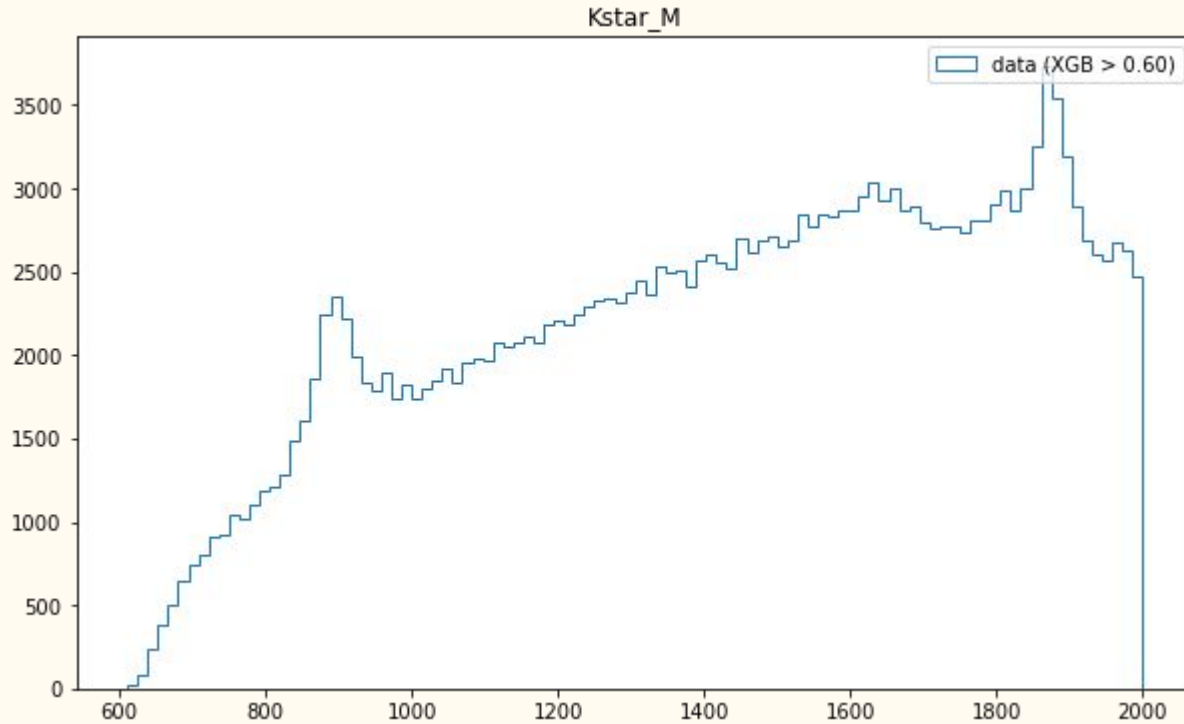
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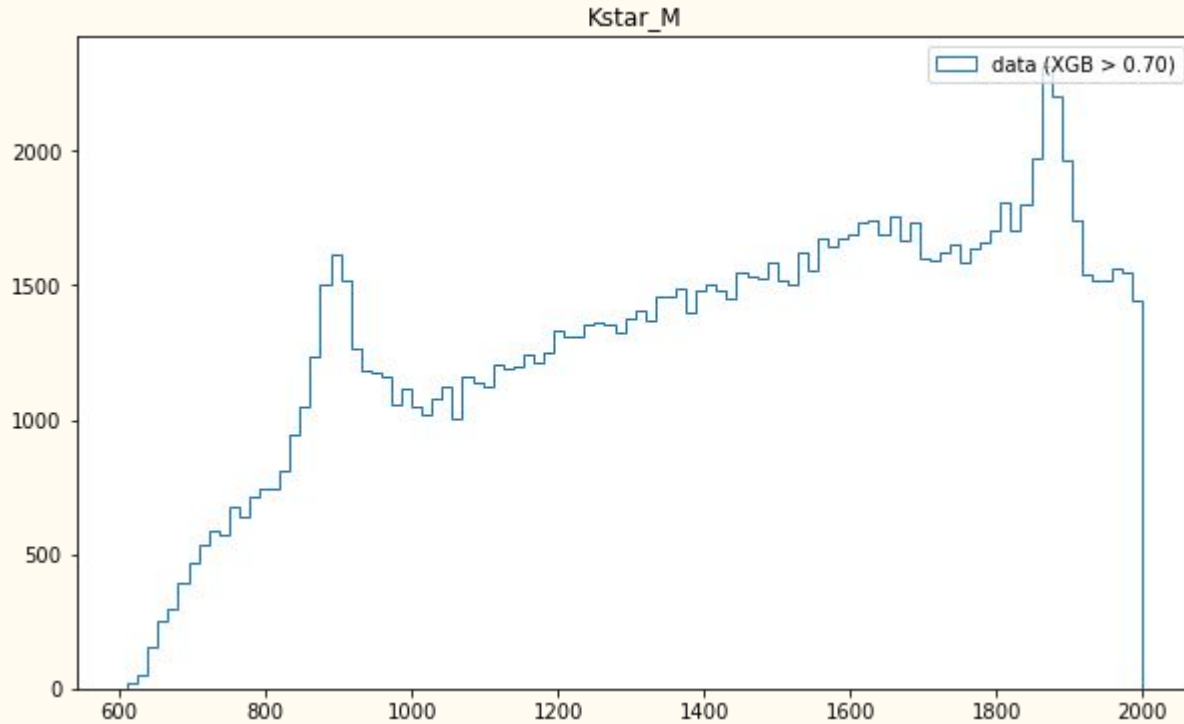
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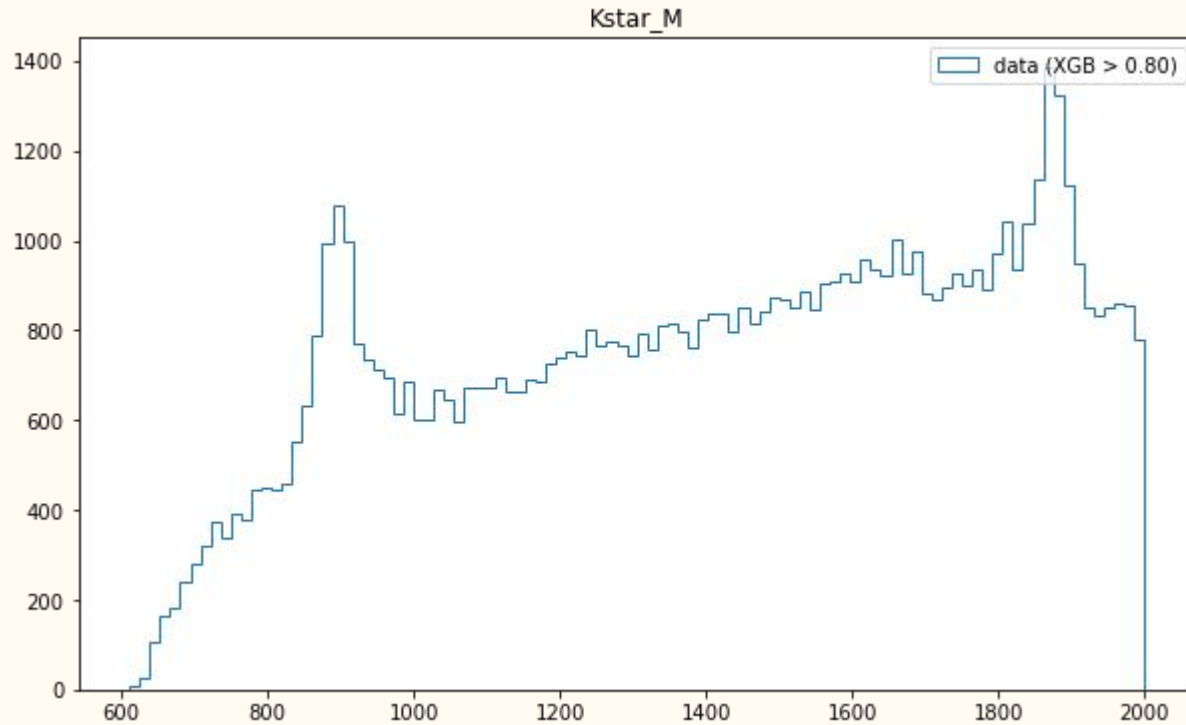
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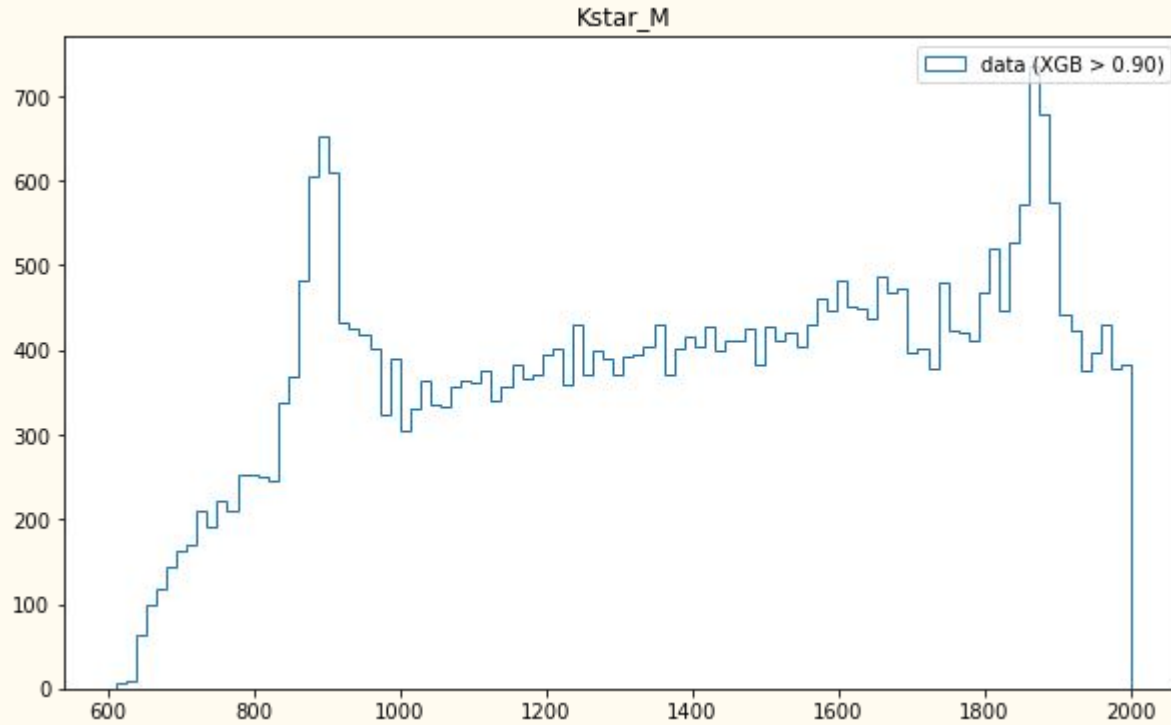
Plots for reference channel



Plots for reference channel



Plots for reference channel



Summary

The pipeline was successfully applied to control channel and it shows very good performance. Next thing to do is application to signal channel.

Questions?

Thank you for your attention

